

POSITIVE SOLUTION CURVES OF AN INFINITE SEMIPOSITONE PROBLEM

RAJENDRAN DHANYA

Communicated by Ratnasingham Shivaji

ABSTRACT. In this article we consider the infinite semipositone problem $-\Delta u = \lambda f(u)$ in Ω , a smooth bounded domain in \mathbb{R}^N , and $u = 0$ on $\partial\Omega$, where $f(t) = t^q - t^{-\beta}$ and $0 < q, \beta < 1$. Using stability analysis we prove the existence of a connected branch of maximal solutions emanating from infinity. Under certain additional hypothesis on the extremal solution at $\lambda = \Lambda$ we prove a version of Crandall-Rabinowitz bifurcation theorem which provides a multiplicity result for $\lambda \in (\Lambda, \Lambda + \epsilon)$.

1. INTRODUCTION

Consider the infinite semi-positone problem

$$\begin{aligned} -\Delta u &= \lambda f(u) && \text{in } \Omega \\ u &> 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega. \end{aligned} \tag{1.1}$$

where $f(t) = t^q - t^{-\beta}$, $0 < q < 1$ and $\beta \in (0, 1)$ and λ a positive parameter. Here Ω is assumed to be a bounded domain with smooth boundary in \mathbb{R}^N . Note that $f(0) = -\infty$ (hence the name infinite semipositone problem) and f is an increasing concave function in \mathbb{R}^+ . Finding a positive solution for semipositone problems are always challenging and in fact proving the existence of multiple positive solutions are even more difficult. The existence of a positive solution for (1.1) when λ large is studied using sub-super solutions technique in [18]. Later in [10], it was additionally shown that when λ is large there exists a maximal positive solution for (1.1) which is in fact bounded below by the distance function $d(x, \partial\Omega) = \inf\{|x - y| : y \in \partial\Omega\}$. The aim of this work is to further understand this maximal branch of solution of (1.1) which emanates from ∞ .

Definition 1.1. We say u is a solution of (1.1), if $u \in C^2(\Omega) \cap C_0^1(\overline{\Omega})$ and $u(x) \geq c d(x, \partial\Omega)$ for some positive constant $c = c(\lambda)$.

Suppose that $\partial\Omega$ is smooth and u is a solution of (P_λ) , then the outward normal derivative $\frac{\partial u}{\partial \nu}(x_0) < 0$ for all $x_0 \in \partial\Omega$. Conversely if we assume that $\frac{\partial u}{\partial \nu}|_{\partial\Omega} < 0$ then by the tubular neighbourhood lemma $u(x) \geq c, d(x, \partial\Omega)$ for some $c > 0$.

2010 *Mathematics Subject Classification.* 35J25, 35J61, 35J75.

Key words and phrases. Semipositone problems; topological methods; bifurcation theory.

©2018 Texas State University.

Submitted May 3, 2018. Published November 1, 2018.

Definition 1.2. Let $\mathcal{S} = \{(\lambda, u_\lambda) : u_\lambda \text{ is a solution to (1.1), as in Definition 1.1}\}$ and let $\Lambda = \inf\{\lambda > 0 : (1.1) \text{ admits at least one solution}\}$.

Definition 1.3. We say $\lambda_\infty = \infty$ is a bifurcation point at infinity for (1.1) if there exists a sequence $(\lambda_n, u_{\lambda_n}) \in \mathcal{S}$ such that $\lambda_n \rightarrow \lambda_\infty$ and $\|u_{\lambda_n}\| \rightarrow \infty$.

The principal eigenvalue of the linearized operator associated to (1.1) is denoted by $\Lambda_1(\lambda)$ and defined as

$$\Lambda_1(\lambda) = \inf_{\varphi \in H_0^1(\Omega), \|\varphi\|_2=1} \left(\int_{\Omega} |\nabla \varphi|^2 - \lambda \int_{\Omega} f'(u)\varphi^2 \right). \quad (1.2)$$

where u solves (1.1) as in definition 1.1. Since the solution $u(x)$ behaves like $d(x)$ near $\partial\Omega$, by Hardy's inequality the term $\int_{\Omega} f'(u)\varphi^2$ make sense. The functional $\int_{\Omega} |\nabla \varphi|^2 - \lambda \int_{\Omega} f'(u)\varphi^2$ is bounded below and coercive on the set $\{\varphi \in H_0^1(\Omega) : \|\varphi\|_2 = 1\}$ and hence a minimizer exists. Also one can show that $\Lambda_1(\lambda)$ satisfies the differential equation $-\Delta\psi - \lambda f'(u)\psi = \Lambda_1(\lambda)\psi$ for some non-negative $\psi \in H_0^1(\Omega)$. We say that a solution u of (1.1) is stable if $\Lambda_1(\lambda)$ is strictly positive. Our main result is the following theorem.

Theorem 1.4. *Assume that Ω is a bounded open set in \mathbb{R}^N with smooth boundary and consider the infinite semipositone problem (1.1) $-\Delta u = \lambda(u^q - u^{-\beta})$ in Ω for $0 < q, \beta < 1$ and $u = 0$ on $\partial\Omega$.*

- (a) *There exists a $\Lambda \in (0, \infty)$ and for all $\lambda > \Lambda$, there exists a maximal positive solution u_λ solving (1.1). And $\|u_\lambda\|_\infty \rightarrow \infty$ as $\lambda \rightarrow \infty$, i.e. λ_∞ is a bifurcation point at infinity. Also if $\lambda \in (0, \Lambda)$, the problem (1.1) does not admit any positive solution.*
- (b) *The maximal solution u_λ is stable for all $\lambda > \Lambda$.*
- (c) *There exists an unbounded connected branch \mathcal{C} of solutions of (1.1) emanating from (∞, ∞) consisting of the maximal solution u_λ . The map $(\Lambda, \infty) \ni \lambda \rightarrow u_\lambda$ is of class C^2 in $\mathbb{R} \times C_e(\bar{\Omega})$.*

We prove results (a) and (b) in Section 2 (see Theorems 2.1 and 2.5). We introduce the operator \mathcal{A} and the space $C_e(\bar{\Omega})$ in section 3 and prove the differentiability of the map \mathcal{A} (in fact we prove \mathcal{A} is a C^2 map) in the Appendix. Using the stability analysis and smoothness of the map \mathcal{A} we prove (c) in Theorem 3.3. Existence of a positive solution for large λ for similar problems are well studied in literature. For example Shi-Yao[21] and Hernández et al. [16] consider the semipositone problem of the type $-\Delta u = \lambda u^q - u^{-\beta}$ with Dirichlet boundary condition in an arbitrary smooth domain Ω and establish the existence of positive solution bounded below by the distance function using sub-super solution techniques. We also use similar techniques to prove the existence of solution for large λ , but here in this work we additionally show that the maximal solution curve $\lambda \rightarrow u_\lambda$ is in fact smooth. Also see [19, 9, 14] for related problems where they prove stability results for infinite semipositone problems. In [2] the authors discuss a bifurcation phenomenon for semipositone problems ($f(0) \in (-\infty, 0)$) depending on the behaviour of $f(t)$ at infinity, i.e. depending on if f is sublinear, superlinear or asymptotically linear at infinity. Positive solutions curves of concave semipositone problems are also studied in [8] and [7].

In Section 4, existence of a non-negative weak solution at $\lambda = \Lambda$ is proved using a limiting argument (see Proposition 4.1). We conclude our paper by proving the following result.

Theorem 1.5. *Either of the following two alternatives hold:*

- (a) *The extremal solution $u_\Lambda(x)$ does not belong to the interior of $C_\epsilon(\bar{\Omega})$, or*
- (b) *The point $\lambda = \Lambda$ is a bifurcation point, i.e. there exists a C^2 curve $(\lambda(s), u(s)) \in \mathcal{S}$ where $s \in (-\epsilon, \epsilon)$ with $\lambda(0) = \Lambda$, $\lambda'(0) = 0$, $\lambda''(0) < 0$ and $u(0) = u_\Lambda$.*

To the best of our knowledge a complete bifurcation diagram for semipositone problem is understood in either of the following two situations: (a) in case of $f(0) = -\infty$ and dimension $N = 1$ (see [17]) or (b) in case of strictly semipositone problems, i.e. $-\infty < f(0) < 0$ in a ball (see [6]). In the latter work the results were obtained by using shooting methods for ODE as any positive solution for a semipositone problem in a ball is known to be radially symmetric. In Theorem 1.5 we make an attempt to understand the bifurcation curve in arbitrary domain Ω under certain additional hypothesis on extremal function u_Λ . The second alternative gives a precise description of the bifurcation branch at $\lambda = \Lambda$. At least in dimension $N = 1$ and $\beta \in (0, \frac{1}{2})$, it is clear from [17, Theorem 2] that the first case does not arise. The second alternative also suggests the existence of multiple positive solutions for (1.1) when $\lambda \in (\Lambda, \Lambda + \epsilon)$ for some $\epsilon > 0$. In fact the solution in the lower branch (the non-maximal solution) is also bounded below by $\tilde{c}(\lambda)d(x, \partial\Omega)$. It is expected that the solutions exhibit a "free boundary" condition (i.e. a non negative solution becomes zero in a set of positive measure) beyond $\Lambda + \epsilon$.

2. STABILITY ANALYSIS

Theorem 2.1. *There exists a $\Lambda \in (0, \infty)$ and for all $\lambda > \Lambda$, there exists a positive function u_λ solving (1.1) as defined in 1.1. In fact, the function u_λ is the maximal solution for (1.1).*

Proof. For λ large enough the existence of a positive solution bounded below by $d(x, \partial\Omega)$ is obtained in Section 5 of [10] for more general nonlinear function f . Here we briefly explain the sub and supersolution to be chosen for our particular nonlinearity $f(t) = t^q - t^{-\beta}$. Following the lines of proof of [10, Example 5.6] we define $\psi = \lambda^r(\phi_1 + \phi_1^{\frac{2}{1+\beta}})$, where ϕ_1 is the first eigenfunction of $-\Delta$, and $1 < r < \frac{1}{1-q+\epsilon}$ is chosen so that $-\Delta\psi \leq \lambda(\psi^q - \psi^{-\beta})$. We define a super-solution $\phi = v_\lambda$ where

$$-\Delta v_\lambda = \lambda v_\lambda^q \text{ in } \Omega, \quad v_\lambda = 0 \text{ on } \partial\Omega. \quad (2.1)$$

Then we know that $v_\lambda = \lambda^{\frac{1}{1-q}}v_1$ and hence for large λ we have $\psi \leq \phi$. Now by [10, Theorem 5.5] there exists a maximal solution u_λ in the ordered interval $[\psi, \phi]$. Thus the solution is bounded below by ψ and hence

$$u_\lambda(x) \geq \psi = \lambda^r(\phi_1 + \phi_1^{\frac{2}{1+\beta}}), \quad \text{i.e. } \|u_\lambda\|_\infty \rightarrow \infty \text{ as } \lambda \rightarrow \infty. \quad (2.2)$$

Suppose u is a solution of (1.1). Then, $-\Delta u \leq \lambda u^q$ and by comparison [20, Lemma 2.2] $u \leq v_\lambda$. Thus the u_λ that we constructed via sub-super solution is in fact the maximal positive solution of (1.1). Now define $\Lambda = \inf\{\lambda > 0 : (P_\lambda) \text{ admits at least one solution}\}$. Next we claim that

$$0 < \Lambda < \infty. \quad (2.3)$$

Clearly from our previous discussion $\Lambda < \infty$. We shall now prove that $\Lambda > 0$. Suppose on the contrary that $\Lambda = 0$, then there exists a sequence $(\lambda_m, u_{\lambda_m}) \in \mathcal{S}$ and $\lambda_m \rightarrow 0$. By comparison Lemma we have $0 < u_{\lambda_m} \leq v_{\lambda_m}$. Therefore for large

m , since $v_{\lambda_m} = \lambda_m^{\frac{1}{1-q}} v_1$ we have $0 < u_{\lambda_m} < 1$ and $-\Delta u_{\lambda_m} = \lambda_m(u_{\lambda_m}^q - u_{\lambda_m}^{-\beta}) < 0$. This leads to a contradiction, since by maximum principle any such solution u_{λ_m} has to be necessarily negative and hence $\Lambda > 0$.

Next we claim that for any $\lambda > \Lambda$ there exists at least one solution for (1.1). Fix $\lambda > \Lambda$, then by definition there exists a $\lambda' \in (\Lambda, \lambda)$ such that (1.1) with $\lambda = \lambda'$ admits at least one solution which we call ψ . Note that we do not claim ψ is a sub-solution for (1.1), but still we prove that there exists a $u_\lambda > \psi$ solving (1.1). Clearly, $\psi < v_{\lambda'} < v_\lambda =: u_0$. Let

$$\begin{aligned} -\Delta u_1 &= \lambda(u_0^q - u_0^{-\beta}) \quad \text{in } \Omega \\ u_1 &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

By the standard weak comparison principle for the functions in $W^{2,p}(\Omega)$ we obtain $u_1 < u_0$. We claim that $\psi < u_1 < u_0$. In fact,

$$\begin{aligned} -\Delta(u_1 - \psi) &= \lambda f(u_0) - \lambda' f(\psi) \geq \lambda f(\psi) - \lambda' f(\psi) \\ &= \left(\frac{\lambda - \lambda'}{\lambda'}\right) \lambda' f(\psi) = -\Delta(\delta\psi) \end{aligned}$$

where $\delta = (\lambda - \lambda')/\lambda' > 0$. Thus once again by comparison method we prove the claim. Iteratively if we define the sequence

$$\begin{aligned} -\Delta u_{n+1} &= \lambda(u_n^q - u_n^{-\beta}) \quad \text{in } \Omega \\ u_{n+1} &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

by mathematical induction we can easily prove that

$$\psi < \cdots \leq u_{n+1} \leq u_n \leq \cdots u_1 < u_0.$$

Thanks to the lower and upper bound of the sequence $\{u_n\}$, we have $u_n \in C_0^{1,\gamma}(\bar{\Omega}) \cap C^2(\Omega)$ (see [10, Theorem 5.2] and [13]). Hence the sequence $\{u_n\}$ is bounded say in $H_0^1(\Omega)$ and if we define $u_\lambda = \lim_{n \rightarrow \infty} u_n$, then u_λ is the maximal solution of (1.1). \square

Our next aim is to prove that the principal eigenvalue of the linearized operator about the maximal solution u_λ is positive. As a first step towards it we prove the following proposition.

Proposition 2.2. *The maximal solution u_λ is semi-stable or the principal eigenvalue of the linearized operator*

$$\Lambda_1(\lambda) = \inf_{\varphi \in H_0^1(\Omega), \|\varphi\|_2=1} \left(\int_{\Omega} |\nabla \varphi|^2 - \lambda \int_{\Omega} f'(u_\lambda) \varphi^2 \right) \geq 0.$$

Proof. For a fixed $\lambda > \Lambda$ we consider the ϵ -approximate regular problem

$$\begin{aligned} -\Delta w &= \lambda((w + \epsilon)^q - (w + \epsilon)^{-\beta}) \quad \text{in } \Omega, \\ w &> 0 \quad \text{in } \Omega, \\ w &= 0 \quad \text{on } \partial\Omega. \end{aligned} \tag{2.4}$$

Let

$$-\Delta v_\lambda^\epsilon = \lambda(v_\lambda^\epsilon + \epsilon)^q \text{ in } \Omega \quad v_\lambda^\epsilon > 0 \text{ in } \Omega; \quad v_\lambda^\epsilon = 0 \text{ on } \partial\Omega.$$

It is easy to check that v_λ^ϵ exists and $v_\lambda^\epsilon < v_\lambda$. Note that u_λ and v_λ^ϵ are respectively sub and super solutions of (2.4) and by standard monotone iteration there exists a $w_\epsilon \in [u_\lambda, v_\lambda]$ solving (2.4). In fact w_ϵ is the maximal solution of (2.4). By Hopf's

maximum principle for some $\theta_1 > 0$ we have $w_\epsilon(x) + \theta_1 d(x, \partial\Omega) \leq v_\lambda^\epsilon$. Next we observe that the sequence $\{w_\epsilon\}$ is bounded independent of ϵ since

$$\int_\Omega |\nabla w_\epsilon|^2 \leq \lambda \int_\Omega (w_\epsilon + 1)^{q+1} \leq \lambda \int_\Omega (v_\lambda + 1)^{q+1} < \infty.$$

Clearly w_ϵ converges to some function \tilde{w} which is a weak solution of (1.1) and $u_\lambda \leq \tilde{w} \leq v_\lambda^\epsilon$. Since u_λ is the maximal solution of (1.1) we must have

$$\lim_{\epsilon \rightarrow 0} w_\epsilon = u_\lambda. \tag{2.5}$$

Let us write $f_\epsilon(t) = (t + \epsilon)^q - (t + \epsilon)^{-\beta}$.

Claim: $\Lambda_1^\epsilon(\lambda) = \inf_{\varphi \in H_0^1(\Omega), \|\varphi\|_2=1} (\int_\Omega |\nabla \varphi|^2 - \lambda \int_\Omega f'_\epsilon(w_\epsilon) \varphi^2) \geq 0$. On the contrary suppose that $\Lambda_1^\epsilon(\lambda) < 0$ and $\varphi_\epsilon \in H_0^1(\Omega)$ be the associated non-negative eigenfunction of

$$-\Delta \varphi_\epsilon - \lambda f'_\epsilon(w_\epsilon) \varphi_\epsilon = \Lambda_1^\epsilon(\lambda) \varphi_\epsilon.$$

We will show that $(w_\epsilon + \theta \varphi_\epsilon)$ is a sub solution of (2.4). For a non-negative $\varphi \in H_0^1(\Omega)$,

$$\begin{aligned} & \int_\Omega \nabla(w_\epsilon + \theta \varphi_\epsilon) \nabla \varphi - \lambda \int_\Omega f_\epsilon(w_\epsilon + \theta \varphi_\epsilon) \varphi \\ &= \lambda \int_\Omega f_\epsilon(w_\epsilon) \varphi - f_\epsilon(w_\epsilon + \theta \varphi_\epsilon) \varphi + \theta f'_\epsilon(w_\epsilon) \varphi_\epsilon \varphi + \theta \Lambda_1^\epsilon(\lambda) \int_\Omega \varphi \varphi_\epsilon \\ &= o(\theta) + \theta \Lambda_1^\epsilon(\lambda) \int_\Omega \varphi \varphi_\epsilon \end{aligned}$$

Choosing $\theta > 0$ small enough we have $(w_\epsilon + \theta \varphi_\epsilon)$ is a sub-solution of (2.4). If required we may choose θ smaller so that $w_\epsilon(x) + \theta \varphi_\epsilon \leq v_\lambda^\epsilon$. Thus $w_\epsilon + \theta \varphi_\epsilon$ and v_λ^ϵ forms an ordered pair of sub and super solution of (2.4) and we obtain a solution $\tilde{w}_\epsilon \in [w_\epsilon + \theta \varphi_\epsilon, v_\lambda]$ of (2.4). This contradicts the fact that w_ϵ is the maximal solution of (2.4) and hence the claim is verified. Thus for every $\varphi \in H_0^1(\Omega)$ such that $\|\varphi\|_2 = 1$,

$$\int_\Omega |\nabla \varphi|^2 - \lambda \int_\Omega f'_\epsilon(w_\epsilon) \varphi^2 \geq 0.$$

Now passing through the limit using (2.5) and Hardy's inequality we obtain that $\Lambda_1(\lambda) \geq 0$. □

Proposition 2.3. *The semi-stable solution of (1.1) is unique.*

Proof. Let u_λ be the maximal solution of (1.1) and v_λ be any other solution of (1.1). We know that u_λ is semi-stable by Proposition 2.2 and assume that v_λ is also semi-stable. Then

$$\int_\Omega |\nabla w|^2 \geq \lambda \int_\Omega f'(v_\lambda) w^2$$

for all $w \in H_0^1(\Omega)$. In particular,

$$\int_\Omega |\nabla(u_\lambda - v_\lambda)|^2 \geq \lambda \int_\Omega f'(v_\lambda)(u_\lambda - v_\lambda)^2. \tag{2.6}$$

Since v_λ and u_λ are both the solutions of (1.1)

$$\int_\Omega |\nabla(u_\lambda - v_\lambda)|^2 = \lambda \int_\Omega (f(u_\lambda) - f(v_\lambda))(u_\lambda - v_\lambda). \tag{2.7}$$

Combining the above two equations we have

$$\int_{\Omega} \{f(u_{\lambda}) - f(v_{\lambda}) - f'(v_{\lambda})(u_{\lambda} - v_{\lambda})\} (u_{\lambda} - v_{\lambda}) \geq 0.$$

Since u_{λ} is the maximal solution this implies

$$\int_{\{u_{\lambda} > v_{\lambda}\}} \{f(u_{\lambda}) - f(v_{\lambda}) - f'(v_{\lambda})(u_{\lambda} - v_{\lambda})\} (u_{\lambda} - v_{\lambda}) \geq 0.$$

Since f is strictly concave the above integral is strictly negative if the Lebesgue measure of the set $\{x : u_{\lambda}(x) > v_{\lambda}(x)\}$ is non-zero. Thus $u_{\lambda} \equiv v_{\lambda}$, or the semi-stable solution is unique. \square

Next we shall prove our main result of this section, the maximal u_{λ} is stable. We consider here a different approximate problem (2.8) for a parameter $\theta < 0$.

$$\begin{aligned} -\Delta z &= \lambda(z^q - z^{-\beta} + \theta) && \text{in } \Omega, \\ z &> 0 && \text{in } \Omega, \\ z &= 0 && \text{on } \partial\Omega. \end{aligned} \tag{2.8}$$

Lemma 2.4. *For each $\theta \in (\theta_0, 0)$ there exists a function z_{θ} which is a maximal solution of (2.8). If $\theta < \theta'$ then $z_{\theta} \leq z_{\theta'}$ and $z_{\theta} \neq z_{\theta'}$.*

Proof. Fix a $\lambda \in (\Lambda, \infty)$ and choose $\lambda' \in (\Lambda, \lambda)$. Let

$$-\Delta V_{\lambda} = \lambda \text{ in } \Omega; \quad V_{\lambda} = 0 \text{ in } \partial\Omega$$

and u_{λ} be the maximal solution of (1.1). Define $\underline{z}_{\epsilon} = \frac{\lambda}{\lambda'} u_{\lambda'} - \epsilon V_{\lambda}$. Then for some positive constants C_1, C_2

$$\underline{z}_{\epsilon} - u_{\lambda'} = \left(\frac{\lambda - \lambda'}{\lambda'} \right) u_{\lambda'} - \epsilon V_{\lambda} \geq (C_1 - \epsilon C_2) d(x, \partial\Omega).$$

If we choose $0 < \epsilon < |\theta_0|$ for some small $\theta_0 < 0$, we have $\underline{z}_{\epsilon} > u_{\lambda'}$. For all $\theta \in (\theta_0, 0)$ define

$$\underline{z}_{\theta} = \frac{\lambda}{\lambda'} u_{\lambda'} + \theta V_{\lambda}. \tag{2.9}$$

Then $-\Delta \underline{z}_{\theta} = \lambda(u_{\lambda'}^q - u_{\lambda'}^{-\beta} + \theta) \leq \lambda(\underline{z}_{\theta}^q - \underline{z}_{\theta}^{-\beta} + \theta)$ and hence a sub solution of (2.8). It is easy to check that $\bar{z}_{\theta} = v_{\lambda}$ is a super solution of (2.8) for all $\theta < 0$. Since $u_{\lambda'} < v_{\lambda}$

$$\underline{z}_{\theta} - \bar{z}_{\theta} = \frac{\lambda}{\lambda'} u_{\lambda'} + \theta V_{\lambda} - v_{\lambda} < \frac{\lambda}{\lambda'} v_{\lambda'} - v_{\lambda} = \left(\frac{\lambda}{\lambda'} (\lambda')^{\frac{1}{1-q}} - \lambda^{\frac{1}{1-q}} \right) v_1 < 0.$$

Thus there exists a solution z_{θ} of (2.8) in between the ordered pair $[\underline{z}_{\theta}, \bar{z}_{\theta}]$. As before using comparison lemma one can easily observe that z_{θ} is the maximal solution of (2.8). Now let $\theta < \theta'$ and $z_{\theta}, z_{\theta'}$ be the maximal solutions of (2.8) and (2.8) with $\theta = \theta'$ respectively. Then

$$-\Delta z_{\theta} \leq \lambda(z_{\theta}^q - z_{\theta}^{-\beta} + \theta') \quad \text{and} \quad z_{\theta} \leq \bar{z}_{\theta'}.$$

Since $z_{\theta'}$ is the maximal solution of (2.8) with $\theta = \theta'$ we conclude that $z_{\theta} \leq z_{\theta'}$. \square

Theorem 2.5. *The maximal solution u_{λ} of (1.1) is stable.*

Proof. Let $\Lambda_1^\theta(\lambda)$ denote the principal eigenvalue of (2.8). Repeating the calculations of Proposition 2.2 we can show that $\Lambda_1^\theta(\lambda) \geq 0$. If $\theta_1 < \theta_2$ using the strict concavity of f and Lemma 2.4 we have for all $\varphi \in H_0^1(\Omega)$, $\|\varphi\|_2 = 1$,

$$\int_{\Omega} |\nabla\varphi|^2 - \lambda \int_{\Omega} f'(z_{\theta_1})\varphi^2 < \int_{\Omega} |\nabla\varphi|^2 - \lambda \int_{\Omega} f'(z_{\theta_2})\varphi^2.$$

Since $\inf_{\varphi \in H_0^1(\Omega)} \int_{\Omega} |\nabla\varphi|^2 - \lambda \int_{\Omega} f'(z_{\theta})\varphi^2$ is attained, we have $\Lambda_1^{\theta_1}(\lambda) < \Lambda_1^{\theta_2}(\lambda)$. Observe that $z_{\theta} \rightarrow u_{\lambda}$ as $\theta \rightarrow 0^-$ and $\lim_{\theta \rightarrow 0^-} \Lambda_1^{\theta}(\lambda) = \Lambda_1(\lambda)$. Thus

$$\Lambda_1(\lambda) > \Lambda_1^{\theta}(\lambda) \geq 0$$

which is the main result. □

3. BIFURCATION ANALYSIS

In the previous section we have shown that for each $\lambda > \Lambda$ there exists a maximal solution for (1.1). In this section we try to understand this maximal branch of solution using bifurcation theory. For $\lambda > \Lambda$, consider the function $u_{\lambda'}$ which is a solution of (1.1) with $\lambda = \lambda'$ for some $\lambda' \in [\Lambda, \lambda)$ and v_{λ} as in (2.1). To ease notation we omit the subscript λ and denote $\psi = \psi_{\lambda} = u_{\lambda'}$ and $\phi = \phi_{\lambda} = v_{\lambda}$, then clearly $\psi < \phi$. Let

$$\mathcal{C}_{\lambda} = \{u \in C_0(\overline{\Omega}) : \psi \leq u \leq \phi\}. \tag{3.1}$$

For each $u \in \mathcal{C}_{\lambda}$ there exists $w \in C_0^1(\overline{\Omega}) \cap C^2(\Omega)$ which is a solution of

$$-\Delta w = \lambda f(u) \text{ in } \Omega, \quad w = 0 \text{ on } \partial\Omega. \tag{3.2}$$

The existence of $w \in W^{2,p}(\Omega)$ easily follows from the lower estimate on u and the regularity of w by [13] (see Section 5 of [10] for the details). Since we would repeatedly use the regularity result of Gui-Lin [13], for the sake of completeness we quote the result below.

Theorem 3.1 (Gui-Lin [13, Prop. 3.4]). *Let Ω be a bounded Lipschitz domain in \mathbb{R}^n , and suppose $u \in C^2(\Omega) \cap C(\overline{\Omega})$ satisfies*

$$|\Delta u(x)| \leq Md(x)^{-\beta} \quad \text{and} \quad |u(x)| \leq Md(x)^{\alpha}$$

for some positive constants M, α . Then there exists some $\gamma \in (0, 1)$ depending upon β and α such that $\|u\|_{C^{1,\gamma}(\overline{\Omega})} \leq C(M, \alpha, \beta)$.

We can in fact prove that the solution w of (3.2) belongs to \mathcal{C}_{λ} . One can observe that $w \leq \phi$ since ϕ is a supersolution of (3.2). It is not clear if ψ is a sub solution of (3.2) or not. But still by the specific choice of ψ we can show that

$$-\Delta(w - \psi) = \lambda f(u) - \lambda' g(\psi) \geq \frac{\lambda - \lambda'}{\lambda'} (-\Delta\psi) \tag{3.3}$$

Since $\lambda' < \lambda$ it follows that $w > \psi$ and hence $w \in \mathcal{C}_{\lambda}$. For a fixed $\lambda \in (\Lambda, \infty)$ we define the map

$$\mathcal{A}:\mathcal{C}_{\lambda} \rightarrow \mathcal{C}_{\lambda} \text{ is defined as } \mathcal{A}(u) = w \text{ if } w \text{ is a solution of (3.2)}. \tag{3.4}$$

We aim to employ the well known abstract setting of bifurcation theory to prove the existence of a connected branch of solutions. If we consider the map $\mathcal{A}:\mathcal{C}_{\lambda} \rightarrow \mathcal{C}_{\lambda}$ it is not possible to use the implicit function theorem since the set $\mathcal{C}_{\lambda} \subset C_0(\overline{\Omega})$ has empty interior. Hence we introduce the space $C_e(\overline{\Omega})$ as in [1] and consider the set \mathcal{C}_{λ} with the topology induced from $C_e(\overline{\Omega})$ in which \mathcal{C}_{λ} has nonempty interior.

Let $e \in C^2(\bar{\Omega})$ denote the unique positive solution of

$$\begin{aligned} -\Delta e &= 1 & \text{in } \Omega \\ e &= 0 & \text{on } \partial\Omega. \end{aligned}$$

Then $e(x) > 0$ in Ω , $\frac{\partial e}{\partial \nu} < 0$ on $\partial\Omega$ and thus $e(x) \geq kd(x, \partial\Omega)$ for some constant $k > 0$. $C_e(\bar{\Omega})$ is the set of functions in $u \in C_0(\bar{\Omega})$ such that $-te \leq u \leq te$ for some $t \geq 0$. $C_e(\bar{\Omega})$ equipped with $\|u\|_e = \inf\{t > 0 : -te \leq u \leq te\}$ is a Banach space. Also the following continuous embedding holds:

$$C_0^1(\bar{\Omega}) \hookrightarrow C_e(\bar{\Omega}) \hookrightarrow C_0(\bar{\Omega}).$$

Further $C_e(\bar{\Omega})$ is an ordered Banach space(OBS) whose positive cone $P_e = \{u \in C_e(\bar{\Omega}) : u(x) \geq 0\}$ is normal and has non empty interior. In particular the interior of P_e consists of all those functions $u \in C(\bar{\Omega})$ with $t_1e \leq u \leq t_2e$ for some $t_1, t_2 > 0$. Define

$$\mathcal{M}_\lambda = \{u \in C_e(\bar{\Omega}) : \psi \leq u \leq \phi\} \quad (3.5)$$

Using the lower and upper bounds for ψ and ϕ in terms of $d(x, \Omega)$ we find that set theoretically \mathcal{C}_λ is same as \mathcal{M}_λ . But topologically they are different and in fact \mathcal{M}_λ has non empty interior which we denote by \mathcal{U}_λ where

$$\mathcal{U}_\lambda = \{u \in \mathcal{M}_\lambda : \psi + t_1e \leq u \leq \phi - t_2e \text{ for some } t_1, t_2 > 0\}. \quad (3.6)$$

By definition the set \mathcal{U}_λ is open and we denote the restriction of the map \mathcal{A} to \mathcal{U}_λ as \mathcal{A} itself. From (3.4) \mathcal{A} maps \mathcal{U}_λ to \mathcal{C}_λ . In the next proposition we prove that \mathcal{A} maps \mathcal{U}_λ to itself and it is a C^2 map.

Proposition 3.2. *The map $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is twice continuously differentiable. The map $\mathcal{A}'(u):C_e(\bar{\Omega}) \rightarrow C_e(\bar{\Omega})$ is continuous linear and compact.*

Proof. Let $u \in \mathcal{U}_\lambda$, i.e there exists some $t_1, t_2 > 0$ such that $\psi + t_1e \leq u \leq \phi - t_2e$ and let $\mathcal{A}(u) = w$. Then $-\Delta(w - \phi) < 0$ in Ω and $w - \phi = 0$ on $\partial\Omega$, and by Hopf Maximum principle there exists a $\tilde{t}_2 > 0$ for which $w \leq \phi - \tilde{t}_2e$. From our previous discussion (3.3) if we take $\tilde{t}_1 = \frac{\lambda - \lambda'}{\lambda}$ we find $w \geq \psi + \tilde{t}_1e$. Thus \mathcal{A} maps \mathcal{U}_λ into itself. Proof of the smoothness of the map \mathcal{A} and the compactness of $\mathcal{A}'(u)$ is much technical and we shall give the details in the Appendix. \square

Next we shall treat λ as a variable and define the map $A:(\Lambda, \infty) \times \mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ as $A(\lambda, u) = w$ if w is a solution of

$$-\Delta w = \lambda f(u) \text{ in } \Omega, \quad w = 0 \text{ on } \partial\Omega. \quad (3.7)$$

Fix λ_1, λ_2 such that $\Lambda < \lambda_1 < \lambda_2 < \infty$. Then for all $\lambda \in [\lambda_1, \lambda_2]$ we can in fact fix the indexed set \mathcal{U}_λ independent of λ in the following way. By the definition of Λ there exists a $\lambda' \in [\Lambda, \lambda_1)$ and (1.1) with $\lambda = \lambda'$ is solvable. Let $\psi = u_{\lambda'}$ and $\phi = v_{\lambda_2}$ and let \mathcal{M}_λ and \mathcal{U}_λ defined as before in (3.5) and (3.6) for this choice of ψ and ϕ . Now \mathcal{U}_λ is independent of λ for all $\lambda \in [\lambda_1, \lambda_2]$. For this particular choice of $\mathcal{U} = \mathcal{U}_\lambda$ we can prove that the map A is C^2 in λ and u variable in $(\lambda_1, \lambda_2) \times \mathcal{U}$.

Theorem 3.3. *There exists a connected branch of positive maximal solutions of (1.1) bifurcating from $\lambda_\infty = \infty$.*

Proof. Fix an open interval $I \subset (\Lambda, \infty)$ and \bar{I} compactly contained in (Λ, ∞) . Let $I = (\lambda_1, \lambda_2)$ and $\psi = u_{\lambda'}$ and $\phi = v_{\lambda_2}$ as before. Thus for all $\lambda \in I$ we define

$\mathcal{M} = \{u \in C_\epsilon(\overline{\Omega}) : \psi \leq u \leq \phi\}$ and \mathcal{U} to be the interior of \mathcal{M} . Consider the map $F: I \times \mathcal{U} \rightarrow \mathcal{U}$ defined as

$$F(\lambda, u) = u - A(\lambda, u). \tag{3.8}$$

Clearly the zeroes of F are the solutions of (1.1) and $F(\lambda, u_\lambda) = 0$ where u_λ is the maximal solution of (1.1). Note that $F: I \times \mathcal{U} \rightarrow \mathcal{U}$ is a C^2 map and $\partial_u F(\lambda, u) = I - \partial_u A(\lambda, u)$ is a compact perturbation of identity. Fix $\lambda_0 \in I$ and let $u_0 = u_{\lambda_0}$ be the maximal solution of (1.1) with $\lambda = \lambda_0$, then $F(\lambda_0, u_0) = 0$. From Theorem 2.5 we know that u_0 is a stable solution and hence $\partial_u F(\lambda_0, u_0)$ is one-one. Now by Fredholm alternative it is onto as well. Thus the linear map $\partial_u F(\lambda_0, u_0)$ is bijective and continuous, hence by open mapping theorem $\partial_u F(\lambda_0, u_0)$ has a continuous inverse. Now we can apply implicit function theorem around (λ_0, u_0) and deduce that there exists a C^2 curve $(\lambda, u(\lambda)) \in (\lambda_0 - \epsilon, \lambda_0 + \epsilon) \times \mathcal{U}$ such that the set of all solutions of $F(\lambda, u) = 0$ in a neighbourhood of (λ_0, u_0) is given by $(\lambda, u(\lambda))$. Note that this $u(\lambda)$ may be different from the maximal solution u_λ .

If we can show that $\lambda \mapsto u_\lambda$ (where u_λ is the maximal solution) is continuous then by the uniqueness of the solution near (λ_0, u_0) we have a $u(\lambda) = u_\lambda$. On the contrary suppose $\lambda \mapsto u_\lambda$ is not continuous at λ_0 . i.e. there exists a sequence $\lambda_n \rightarrow \lambda_0$ such that $u_{\lambda_n} \not\rightarrow u_0$. One can use Hardy’s inequality to prove that $\{u_{\lambda_n}\}$ is bounded in $H_0^1(\Omega)$ and hence up to a sub sequence $u_{\lambda_n} \rightharpoonup \tilde{u}$ in $H_0^1(\Omega)$. It is also easy to check that \tilde{u} is a solution of (P_{λ_0}) . Since u_0 is the maximal solution of (P_{λ_0}) we have

$$\tilde{u} \leq u_0 \quad \text{and} \quad \tilde{u} \neq u_0. \tag{3.9}$$

On the other hand we have $u(\lambda_n) \rightarrow u_0$ and $u(\lambda_n) \leq u_{\lambda_n}$. Taking limit as $n \rightarrow \infty$ we find $u_0 \leq \tilde{u}$ which contradicts (3.9). We have now $u(\lambda) = u_\lambda$ and hence by implicit function theorem $\lambda \rightarrow u_\lambda$ is a C^2 map which completes the proof of theorem. \square

Remark 3.4. The smoothness of the map $\lambda \rightarrow u_\lambda$ for $\lambda \in (\Lambda, \infty)$ is completely determined by the smoothness of the operator \mathcal{A} . We can in fact prove that the map is infinitely many times differentiable, hence $\lambda \rightarrow u_\lambda$ is a C^∞ map.

The proof of our main result now follows from Theorem 2.1, equations (2.2), (2.3), Theorems 2.5, 3.3 and Remark 3.4.

4. BIFURCATION ANALYSIS AT $\lambda = \Lambda$

Proposition 4.1. *There exists a non-negative solution u_Λ solving (1.1) with $\lambda = \Lambda$ in the weak sense. The Lebesgue measure of the set $\{x : u_\Lambda(x) = 0\}$ is zero.*

Proof. Let $\{u_n\}$ denote the sequence of maximal solutions of (P_{λ_n}) where $\lambda_n \downarrow \Lambda$ and $\lambda_n < \bar{\lambda}$. If \bar{v} denote the solution of (2.1) for $\lambda = \bar{\lambda}$, we have $0 < u_{n+1} \leq u_n \leq \bar{v}$ and

$$\int_\Omega |\nabla u_n|^2 = \lambda_n \int_\Omega (u_n^{q+1} - u_n^{1-\beta}) \leq \lambda_n \int_\Omega u_n^{q+1} \leq \bar{\lambda} \int_\Omega \bar{v}^{q+1}. \tag{4.1}$$

Thus the sequence $\{u_n\}$ is bounded in $H_0^1(\Omega)$ and denote the weak limit of u_n as

$$u_\Lambda := \lim_{n \rightarrow \infty} u_n. \tag{4.2}$$

We will show that u_Λ is in fact a solution of (1.1) with $\lambda = \Lambda$ in the weak sense. As a first step we shall prove that $\{x \in \Omega : u_\Lambda(x) = 0\}$ has Lebesgue measure zero. Let ϕ_1 be the first eigenfunction of $-\Delta$ and $\gamma \in (0, 1), \epsilon > 0$. Consider the function

$\psi = (\phi_1 + \epsilon)^\gamma - \epsilon^\gamma \in H_0^1(\Omega)$. Then from a direct computation we find $-\Delta\psi \geq 0$ and hence $\langle -\Delta u_n, \psi \rangle_{H_0^1(\Omega) \times H^{-1}(\Omega)} \geq 0$ which implies

$$\lambda_n \int_{\Omega} (u_n^q - u_n^{-\beta}) \psi \geq 0. \quad (4.3)$$

Thus

$$\int_{\Omega} u_n^{-\beta} ((\phi_1 + \epsilon)^\gamma - \epsilon^\gamma) \leq \int_{\Omega} u_n^q ((\phi_1 + \epsilon)^\gamma - \epsilon^\gamma).$$

Now letting $\epsilon \rightarrow 0$ and $\gamma \rightarrow 0$ we have $\int_{\Omega} u_n^{-\beta} \leq \int_{\Omega} u_n^q \leq \int_{\Omega} \bar{v}^q < \infty$. Once again using Fatou's lemma,

$$\int_{\Omega} u_{\Lambda}^{-\beta} < \infty \quad (4.4)$$

which in turn implies $\{x \in \Omega : u_{\Lambda}(x) = 0\}$ is of Lebesgue measure zero. Now we will prove that u_{Λ} is a weak solution of (1.1) with $\lambda = \Lambda$. We have

$$\int_{\Omega} \nabla u_n \nabla \varphi = \lambda_n \int_{\Omega} (u_n^q - u_n^{-\beta}) \varphi \quad \text{for all } \varphi \in C_c^\infty(\Omega).$$

The only difficulty arises while passing through the limit in the term involving $u_n^{-\beta}$. But note that $u_n^{-\beta} |\varphi| \leq u_{\Lambda}^{-\beta} \|\varphi\|_{\infty} \in L^1(\Omega)$ and by dominated convergence theorem u_{Λ} is a weak solution of (1.1) with $\lambda = \Lambda$. \square

Next we shall discuss a sufficient condition that ensures the existence of multiple solutions for (1.1). We make a crucial assumption that the non-negative solution u_{Λ} belongs to $C_e(\bar{\Omega})$ and is bounded below by $cd(x, \partial\Omega)$ for some $c > 0$. By the above assumption u_{Λ} is positive and it can be shown that the (1.1) with $\lambda = \Lambda$ admits a unique positive solution. Indeed, if \tilde{u}_{Λ} is another positive solution of (1.1) with $\lambda = \Lambda$ then we can show that a convex combination of u_{Λ} and \tilde{u}_{Λ} is a positive solution of (1.1) with $\lambda = \lambda'$ for some $\lambda' < \Lambda$ which is impossible (see [19, Proposition 5] for details). Now the uniqueness in the class of positive solutions imply that u_{Λ} is maximal and by Proposition 2.2, $\Lambda_1(\Lambda) = 0$. Indeed, since u_{Λ} is maximal it is clear that $\Lambda_1(\Lambda) \geq 0$. Suppose $\Lambda_1(\Lambda) > 0$, then implicit function theorem would guarantee the existence of a positive solution for some $\lambda < \Lambda$ which would contradict the definition of Λ . Next we shall prove a local bifurcation result of Crandall-Rabinowitz [3] for an infinite semipositone problem. Similar ideas of the proof were used in [4, 11] when the authors studied a positone convex non-linearity.

Lemma 4.2. *The solutions of $F(\lambda, u) = 0$ near (Λ, u_{Λ}) are described by a curve $(\lambda(s), u(s)) = (\Lambda + \tau(s), u_{\Lambda} + s\phi_{\Lambda} + x(s))$ where $s \rightarrow (\tau(s), x(s)) \in \mathbb{R} \times C_e(\bar{\Omega})$ is a continuously differentiable function near $s = 0$ with $\tau(0) = \tau'(0) = 0$, $\tau''(0) > 0$ and $x(0) = x'(0) = 0$. Moreover τ is of class C^2 near 0.*

Proof. Consider the map $F(\lambda, u)$ and the Gateaux derivative of F at (Λ, u_{Λ}) . Clearly $\partial_{\lambda} F(\Lambda, u_{\Lambda}) = -\partial_{\lambda} A(\Lambda, u_{\Lambda}) = -\frac{u_{\Lambda}}{\Lambda}$. Now consider the null space of the linear operator $\partial_u F(\Lambda, u_{\Lambda})$. Since $\Lambda_1(\Lambda) = 0$, there exists a $\phi_{\Lambda} \in H_0^1(\Omega)$ such that

$$\begin{aligned} -\Delta \phi_{\Lambda} &= \Lambda f'(u_{\Lambda}) \phi_{\Lambda} \quad \text{in } \Omega, \\ \phi_{\Lambda} &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

By the interior regularity results the eigenfunction $\phi_{\Lambda} \in C^2(\Omega) \cap H_0^1(\Omega)$ itself. Now by [12, Theorem 8.16], the principal eigenvalue $\Lambda_1(\Lambda)$ is simple and the corresponding eigenfunction ϕ_{Λ} is positive. Hence $\ker(\partial_u F(\Lambda, u_{\Lambda}))$ is one dimensional and is

spanned by ϕ_Λ . We claim that $\partial_\lambda F(\Lambda, u_\Lambda) \notin \ker \partial_u F(\Lambda, u_\Lambda)$. If so, then for some constant k we have $u_\Lambda = k\phi_\Lambda$. This implies $f(u_\Lambda) = kf'(u_\Lambda)\phi_\Lambda$ which is impossible since RHS is has a constant sign and LHS changes its sign inside Ω and hence that $\partial_\lambda F(\Lambda, u_\Lambda) \notin \ker \partial_u F(\Lambda, u_\Lambda)$.

Let X be any complement of the span of $\{\phi_\Lambda\}$ in $C_e(\overline{\Omega})$ and the map $\theta: \mathbb{R} \times \mathbb{R} \times X \rightarrow C_e(\overline{\Omega})$ be defined as

$$\theta(s, \tau, x) = F(\Lambda + \tau, u_\Lambda + s\phi_\Lambda + x)$$

Then, we claim that $\partial_{\tau,x}\theta(0, 0, 0) = (\partial_\lambda F(\Lambda, u_\Lambda), \partial_u F(\Lambda, u_\Lambda))$ is an isomorphism from $\mathbb{R} \times X$ on to X . Since $\partial_\lambda F(\Lambda, u_\Lambda) \notin \text{Range } \partial_u F(\Lambda, u_\Lambda)$ the map $\partial_{\tau,x}\theta(0, 0, 0)$ is one-one in $\mathbb{R} \times X$. Now by Fredholm alternative $\partial_{\tau,x}\theta(0, 0, 0)$ is also onto. Now by implicit function theorem there exists an $\epsilon > 0$ and a C^2 function $p: (-\epsilon, \epsilon) \rightarrow \mathbb{R} \times X$ such that $p(s) = (\tau(s), x(s))$ and $\theta(s, p(s)) = 0$, $\tau(0) = 0$ and $x(0) = 0$. i.e., $F(\Lambda + \tau(s), u_\Lambda + s\phi_\Lambda + x(s)) = 0$. Now differentiating with respect to s variable and evaluating at $s = 0$, we obtain

$$\partial_\lambda F(\Lambda, u_\Lambda)\tau'(0) + \partial_u F(\Lambda, u_\Lambda)x'(0) = 0.$$

Since $\partial_\lambda F(\Lambda, u_\Lambda) \notin \text{Range}(\partial_u F(\Lambda, u_\Lambda))$ we have $\tau'(0) = x'(0) = 0$. Once again differentiating $F(\Lambda + \tau(s), u_\Lambda + s\phi_\Lambda + x(s))$ we obtain

$$\partial_\lambda F(\Lambda, u_\Lambda)\tau''(0) + \partial_{uu}F(\Lambda, u_\Lambda)\phi_\Lambda^2 + \partial_u F(\Lambda, u_\Lambda)x''(0) = 0. \tag{4.5}$$

Let us write the middle term in the above expression as $W = \partial_{uu}F(\Lambda, u_\Lambda)\phi_\Lambda^2$. Then one can easily check that

$$\begin{aligned} \Delta W &= \Lambda f''(u_\Lambda)\phi_\Lambda^2 \quad \text{in } \Omega, \\ W &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Since f is concave, by maximum principle $W \geq 0$. Now call $w = \partial_u F(\Lambda, u_\Lambda)x''(0)$ which by definition is equal to $x''(0) - \partial_u A(\Lambda, u_\Lambda)x''(0)$. If $w_1 = \partial_u A(\Lambda, u_\Lambda)x''(0)$ then w_1 solves

$$\begin{aligned} -\Delta w_1 &= \Lambda f'(u_\Lambda)x''(0) \quad \text{in } \Omega, \\ w_1 &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Thus $\int_\Omega \nabla w_1 \nabla \phi_\Lambda = \int_\Omega \Lambda f'(u_\Lambda)x''(0)\phi_\Lambda$. From the definition of ϕ_Λ , we also have $\int_\Omega \nabla w_1 \nabla \phi_\Lambda = \int_\Omega \Lambda f'(u_\Lambda)w_1\phi_\Lambda$. Thus

$$\int_\Omega \Lambda f'(u_\Lambda)\phi_\Lambda w = 0.$$

Now multiplying (4.5) by $\Lambda f'(u_\Lambda)\phi_\Lambda$ and integrating over Ω ,

$$-\tau''(0) \int_\Omega u_\Lambda f'(u_\Lambda)\phi_\Lambda + \int_\Omega W \Lambda f'(u_\Lambda)\phi_\Lambda = 0.$$

We know f is monotonically increasing and ϕ_Λ is a non-negative function and $W \geq 0$. Thus $\tau'' \geq 0$ which completes the proof. \square

Proof of Theorem 1.5. Suppose that alternative (a) does not hold. Then from the properties of $C_e(\overline{\Omega})$ (see Section 3) there exists a constant $c_\Lambda > 0$ such that $u_\Lambda(x) \geq c_\Lambda d(x, \partial\Omega)$. Thus $\Lambda_1(\Lambda)$ is well defined and is non-negative. Now by the definition of Λ the principal eigenvalue $\Lambda_1(\Lambda)$ cannot be positive and hence the proof of Lemma 4.2 is applicable and which completes the Theorem 1.5. \square

5. APPENDIX

Proposition 5.1. *The map $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is a C^2 map.*

Proof. Let $u \in \mathcal{U}_\lambda$, i.e. there exists some $t_1, t_2 > 0$ such that $\psi + t_1e \leq u \leq \phi - t_2e$ and let $\mathcal{A}(u) = w$. Then $-\Delta(w - \phi) < 0$ in Ω and $w - \phi = 0$ on $\partial\Omega$, and by Hopf Maximum principle there exists a $\tilde{t}_2 > 0$ for which $w \leq \phi - \tilde{t}_2e$. From our previous discussion (3.3) if we take $\tilde{t}_1 = \frac{\lambda - \lambda'}{\lambda}$ we find $w \geq \psi + \tilde{t}_1e$. Thus \mathcal{A} maps \mathcal{U}_λ into itself.

Step I. $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is continuous. Let $h \in C_e(\bar{\Omega})$ with $\|h\|_{C_e(\bar{\Omega})}$ small so that $u+h \in \mathcal{U}_\lambda$ and $\mathcal{A}(u+h) = w_h$. Then $(w_h - w)$ satisfies $-\Delta(w_h - w) = \lambda(f(u+h) - f(u))$ in Ω and $w_h - w = 0$ on $\partial\Omega$. For $p \in (1, \frac{1}{\beta})$ using L^p estimate and dominated convergence theorem we find

$$\|w_h - w\|_{W^{2,p}(\Omega)} \leq C\|f(u+h) - f(u)\|_{L^p(\Omega)} \rightarrow 0 \quad \text{as } \|h\|_{C_e(\bar{\Omega})} \rightarrow 0. \tag{5.1}$$

Now since w_h and w belongs to \mathcal{U}_λ we have $|w_h - w| \leq Cd(x, \partial\Omega)$. Now we can apply Theorem 3.1 and obtain $\|w_h - w\|_{C^{1,\gamma}(\Omega)}$ is bounded. Thanks to Ascoli-Arzela theorem and (5.1) we have $w_h \rightarrow w$ in $C_0^1(\bar{\Omega})$. Finally using the continuity of the embedding $C_0^1(\bar{\Omega}) \hookrightarrow C_e(\bar{\Omega})$ we conclude that $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is continuous.

Step II. The map $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is C^1 . For a given $u \in \mathcal{U}_\lambda$ and $h \in C_e(\bar{\Omega})$ consider the solution operator z defined as

$$-\Delta z = \lambda f'(u)h \text{ in } \Omega \quad \text{and} \quad z = 0 \text{ on } \partial\Omega. \tag{5.2}$$

Let us denote $\xi_\lambda \in C_0^1(\bar{\Omega}) \cap C^2(\Omega)$ be the unique solution of

$$-\Delta \xi_\lambda = \lambda \xi_\lambda^{-\beta} \text{ in } \Omega \quad \text{and} \quad \xi_\lambda = 0 \text{ on } \partial\Omega.$$

The existence and behaviour of the solution ξ_λ near $\partial\Omega$ is studied in [5]. It is well known that $\xi_\lambda \sim d(x, \partial\Omega)$ and $d(x, \partial\Omega) \sim e(x)$ and thus $\xi_\lambda \sim e(x)$. We can estimate $f'(u)h$ in terms of ξ_λ as

$$|f'(u)h| \leq C_0 \cdot e(x)^{-(\beta+1)} |h(x)| \leq \frac{C_1 \|h\|_{C_e(\bar{\Omega})}}{\xi_\lambda^\beta}$$

for some positive constant C_1 . Thus,

$$C_1 \|h\| \Delta \xi_\lambda \leq -\Delta z = \lambda f'(u)h \leq \lambda C_1 \|h\| \xi_\lambda^{-\beta} = -C_1 \|h\| \Delta \xi_\lambda,$$

By the comparison principle and since $\xi_\lambda(x) \sim e(x)$ we have for some $C > 0$,

$$|z(x)| \leq C \|h\|_{C_e(\bar{\Omega})} e(x) \tag{5.3}$$

Now as in Step I, let $w_h = A(u+h)$ and $w = A(u)$, then using Taylor's theorem

$$-\Delta(w_h - w - z) = \lambda f''(u + \theta h) \frac{h^2}{2} \quad \text{for some } \theta(x) \in (0, 1).$$

Since $|f''(u + \theta h)h^2| \leq C \|h\|_{C_e(\bar{\Omega})}^2 e(x)^{-\beta}$ we have

$$\left\| \frac{w_h - w - z}{\|h\|_{C_e(\bar{\Omega})}} \right\|_{W^{2,p}(\Omega)} \leq C \|h\|_{C_e(\bar{\Omega})}.$$

Up to a sub sequence $(w_h - w - z)/\|h\|_{C_e(\bar{\Omega})}$ converges to 0 as $\|h\|_{C_e(\bar{\Omega})} \rightarrow 0$. It can be shown that $|w_h - w - z|/\|h\|_{C_e(\bar{\Omega})} \leq Cd(x, \partial\Omega)$ and thus $(w_h - w - z)/\|h\|_{C_e(\bar{\Omega})}$

satisfies the assumptions of theorem 3.1. Hence,

$$\frac{w_h - w - z}{\|h\|_{C_e(\bar{\Omega})}} \text{ is bounded in } C^{1,\gamma}(\bar{\Omega}) \quad (5.4)$$

Now by using Ascoli-Arzela theorem and continuity of the embedding $C_0^1(\Omega) \hookrightarrow C_e(\bar{\Omega})$ we deduce that $\frac{w_h - w - z}{\|h\|_{C_e(\bar{\Omega})}} \rightarrow 0$ in $C_e(\bar{\Omega})$. If we call $\mathcal{A}'(u)h = z$ then

$$\|\mathcal{A}(u+h) - \mathcal{A}(u) - \mathcal{A}'(u)h\|_{C_e(\bar{\Omega})} = o(\|h\|).$$

Now from (5.3) we note that $\mathcal{A}'(u):C_e(\bar{\Omega}) \rightarrow C_e(\bar{\Omega})$ is a bounded linear map and hence the map $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is differentiable. It remains to show that \mathcal{A} is continuously differentiable, i.e. $u \rightarrow \mathcal{A}'(u)$ is continuous. Let $\tilde{u} \in C_e(\bar{\Omega})$ such that $\|\tilde{u} - u\| < \delta$ and $\mathcal{A}'(\tilde{u})h = \tilde{z}$ for some $h \in C_e(\bar{\Omega})$. Using Taylor's theorem there exists some $\theta(x) \in [u, \tilde{u}]$ and

$$|f'(\tilde{u}) - f'(u)| = \lambda |f''(\theta)| |(\tilde{u} - u)h| \leq \frac{C_0 e(x)^2}{d(x)^{\beta+2}} \delta \|h\|_{C_e(\bar{\Omega})} \leq \frac{C_1 \delta}{\xi_1^\beta} \|h\|_{C_e(\bar{\Omega})}$$

where the constant C_1 is independent of u and \tilde{u} . As before estimating $-\Delta(\tilde{z} - z)$ from above and below and using maximum principle we have $|\tilde{z}(x) - z(x)| \leq C\delta \|h\|_{C_e(\bar{\Omega})}$. Now taking supremum over $\|h\|_{C_e(\bar{\Omega})} \leq 1$ we have

$$\|\mathcal{A}'(\tilde{u}) - \mathcal{A}'(u)\| \leq C\|\tilde{u} - u\|_{C_e(\bar{\Omega})}$$

and thus \mathcal{A} is continuously differentiable.

Step III. The map \mathcal{A} is C^2 . Now that we have proved $\mathcal{A}:\mathcal{U}_\lambda \rightarrow \mathcal{U}_\lambda$ is C^1 , using the same idea we can prove that \mathcal{A} is twice continuously differentiable. In order to avoid the repetition of the same arguments we skip the details of the proof of step III. \square

From (5.4) of above proposition we know that $\|\frac{w_h - w - z}{\|h\|}\|_{C^{1,\gamma}(\bar{\Omega})}$ is bounded and similarly $\|\frac{w_h - w}{\|h\|}\|_{C^{1,\gamma}}$ is also bounded. So

$$\begin{aligned} \|\mathcal{A}'(u)h\|_{C^{1,\gamma}(\bar{\Omega})} &= \|z\|_{C^{1,\gamma}(\bar{\Omega})} \leq \|w_h - w - z\|_{C^{1,\gamma}(\bar{\Omega})} + \|w_h - w\|_{C^{1,\gamma}(\bar{\Omega})} \\ &= \|h\| \left\| \frac{w_h - w - z}{\|h\|} \right\|_{C^{1,\gamma}(\bar{\Omega})} + \|h\| \left\| \frac{w_h - w}{\|h\|} \right\|_{C^{1,\gamma}(\bar{\Omega})} \\ &\leq M \|h\|_{C_e(\bar{\Omega})} \end{aligned}$$

which implies $\mathcal{A}'(u) \in BL(C_e(\bar{\Omega}), C^{1,\gamma}(\bar{\Omega}))$ and hence $\mathcal{A}'(u):C_e(\bar{\Omega}) \rightarrow C_e(\bar{\Omega})$ is compact.

Corollary 5.2. $\mathcal{A}'(u):C_e(\bar{\Omega}) \rightarrow C_e(\bar{\Omega})$ is continuous linear and compact.

Acknowledgments. This research was supported by INSPIRE faculty fellowship (DST/INSPIRE/04/2015/003221) at the Indian Statistical Institute, Bangalore Centre.

REFERENCES

- [1] H. Amann; *Fixed point equations and nonlinear eigenvalue problems in ordered Banach spaces*, SIAM Rev. 18 (1976), no. 4, 620–709.
- [2] A. Ambrosetti, D. Arcoya, B. Buffoni; *Positive solutions for some semi-positone problems via bifurcation theory*. Differential Integral Equations 7 (1994), no. 3-4, 655–663.
- [3] M. G. Crandall, P. H. Rabinowitz; *Bifurcation from simple eigenvalues*, J. Funct. Anal., 8 (1971), 321–340.

- [4] M. G. Crandall, P. H. Rabinowitz, *Bifurcation, perturbation of simple eigenvalues and linearized stability*. Arch. Rational Mech. Anal. 52 (1973), 161–180.
- [5] M. G. Crandall, P. H. Rabinowitz, L. Tartar; *On a Dirichlet problem with a singular nonlinearity*, Comm. Partial Differential Equations, 2 (1977), 193–222.
- [6] Alfonso Castro, Gadam Sudhasree; *Uniqueness of stable and unstable positive solutions for semipositone problems*. Nonlinear Anal. 22 (1994), no. 4, 425–429.
- [7] Alfonso Castro, Gadam, Sudhasree; R. Shivaji; *Positive solution curves of semipositone problems with concave nonlinearities*. Proc. Roy. Soc. Edinburgh Sect. A 127 (1997), no. 5, 921–934.
- [8] Alfonso Castro, R. Shivaji; *Positive solutions for a concave semipositone Dirichlet problem*. Nonlinear Anal. 31 (1998), no. 1-2, 91–98.
- [9] Juan Davila, Marcelo Montenegro; *Positive versus free boundary solutions to a singular elliptic equation*. J. Anal. Math. 90 (2003), 303–335.
- [10] R. Dhanya, E. Ko, R. Shivaji; *A three solution theorem for singular nonlinear elliptic boundary value problems*. J. Math. Anal. Appl. 424 (2015), no. 1, 598–612.
- [11] R. Dhanya, J. Giacomoni, K. Saoudi, S. Prashanth; *Global bifurcation and local multiplicity results for elliptic equation with singular nonlinearity of super exponential growth in \mathbb{R}^2* . Adv. Differential Equations 17 (2012), No 3-4, 369-400.
- [12] M. Ghergu, V. D. Radulescu; *Singular Elliptic Problems: Bifurcation and Asymptotic Analysis*, Oxford University Press, 2008.
- [13] C. Gui, F.-H. Lin; *Regularity of an elliptic problem with a singular nonlinearity*. Proc. Roy. Soc. Edinburgh Sect. A, 123 (1993), 1021–1029.
- [14] Habib Maagli, Jacques Giacomoni, Paul Sauvy; *Existence of compact support solutions for a quasilinear and singular problem*. Differential Integral Equations 25 (2012), no. 7-8, 629–656.
- [15] J. Hernández, F. Mancebo, J. M. Vega; *On the linearization of some singular nonlinear elliptic problems and applications*. Ann. Inst. H. Poincaré Anal. Non Linéaire, 19 (2002), 777–813.
- [16] J. Hernández, F. Mancebo, J. M. Vega; *Positive solutions for singular nonlinear elliptic equations*. Proc. Roy. Soc. Edinburgh Sect. A 137 (2007), no. 1, 41–62.
- [17] J. I. Díaz, J. Hernández, F. J. Mancebo; *Branches of positive and free boundary solutions for some singular quasilinear elliptic problems*. J. Math. Anal. Appl. 352 (2009), no. 1, 449–474.
- [18] E. K. Lee, R. Shivaji, J. Ye; *Subsolution: A journey from positone to infinite semipositone problems*. Elec. J. Diff. Eqns., Conf. 17 (2009), 123–131.
- [19] Paul Sauvy; *Stability of the solutions for a singular and sublinear elliptic problem*. Twelfth International Conference Zaragoza-Pau on Mathematics, 195-206, Monogr. Mat. Garca Galdeano, 39, Prensas Univ. Zaragoza, Zaragoza, 2014.
- [20] J. Shi, R. Shivaji; *Global bifurcations of concave semipositone problems*. Evolution equations, pp. 385-398, Lecture Notes in Pure and Appl. Math., Vol. 234, Dekker, New York, 2003.
- [21] Junping Shi, Miaoxin Yao; *On a singular nonlinear semilinear elliptic problem*. Proc. Roy. Soc. Edinburgh Sect. A 128 (1998), no. 6, 1389–1401.

RAJENDRAN DHANYA

SCHOOL OF MATHEMATICS AND COMPUTER SCIENCE, INDIAN INSTITUTE OF TECHNOLOGY, GOA
403401, INDIA

E-mail address: dhanya.tr@gmail.com