

STRUCTURAL STABILITY FOR BRINKMAN-FORCHHEIMER EQUATIONS

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ABSTRACT. In this paper, we obtain the continuous dependence and convergence results for the Brinkman and Forchheimer coefficients of a differential equation that models the flow of fluid in a saturated porous medium.

1. INTRODUCTION

The concept of structural stability in which the study of continuous dependence (or stability) is on changes in the model itself rather than the initial data, has been the subject of much recent study. Many references to the work of the nature are given in the monograph of Ames and Straughan [1], which stress that continuous dependence on the model itself, or structural stability, is every bit as important as stability with respect to perturbations of the initial data. In particular, the stability of flow in porous media has attracted much more attention in the literature; see [3, 4, 5, 6, 7, 8] and their references.

In this paper, we are interested in the Brinkman-Forchheimer equations governing the flow of fluid in a saturated porous medium,

$$\begin{aligned} \frac{\partial u_i}{\partial t} &= \lambda \Delta u_i - a u_i - b |u| u_i - p_{,i} \\ \frac{\partial u_i}{\partial x_i} &= 0 \end{aligned} \tag{1.1}$$

where u_i is the average fluid velocity in the porous medium, a is the Darcy coefficient, λ is the Brinkman coefficient, b is the Forchheimer coefficient, and p is the pressure. λ , a and b are positive constants. Here also Δ is the laplace operator, and $\|\cdot\|$ denotes the norm of L^2 .

We assume that Ω is a bounded, simply connected domain with boundary $\partial\Omega$ in R^3 . Associated with (1.1), we imposed the boundary condition

$$u_i = 0 \quad \text{on } \partial\Omega \times \{t > 0\} \tag{1.2}$$

and the initial condition

$$u_i(x, 0) = f_i(x). \tag{1.3}$$

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In this paper, the usual summation convention is employed with repeated Latin subscripts summed from 1 to 3. The comma is used to indicate partial differentiation and the differentiation with respect to the direction x_k is denoted as “ $,k$ ”.

2. CONTINUOUS DEPENDENCE FOR THE BRINKMAN COEFFICIENT

To study the continuous dependence on λ , we let (u_i, p) and (v_i, q) solve the following boundary initial-value problems for different Brinkman coefficients λ_1 and λ_2 ,

$$\begin{aligned} \frac{\partial u_i}{\partial t} &= \lambda_1 \Delta u_i - a u_i - b|u|u_i - p_{,i} \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial u_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ u_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ u_i(x, 0) &= f_i(x), \quad x \in \Omega \end{aligned} \quad (2.1)$$

and

$$\begin{aligned} \frac{\partial v_i}{\partial t} &= \lambda_2 \Delta v_i - a v_i - b|v|v_i - q_{,i} \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial v_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ v_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ v_i(x, 0) &= f_i(x), \quad x \in \Omega \end{aligned} \quad (2.2)$$

We define the difference variables w_i , π and λ by

$$w_i = u_i - v_i, \pi = p - q, \lambda = \lambda_1 - \lambda_2 \quad (2.3)$$

and then (w_i, π) satisfies the boundary initial-value problem

$$\begin{aligned} \frac{\partial w_i}{\partial t} &= \lambda_1 \Delta u_i - \lambda_2 \Delta v_i - a w_i - b(|u|u_i - |v|v_i) - \pi_{,i} \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial w_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ w_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ w_i(x, 0) &= 0, \quad x \in \Omega \end{aligned} \quad (2.4)$$

Multiplying (2.4)₁ by w_i and integrating over Ω , we get

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \|w\|^2 \\ &= - \int_{\Omega} \lambda_1 \nabla u_i \nabla w_i dx + \int_{\Omega} \lambda_2 \nabla v_i \nabla w_i dx - a \|w\|^2 - b \int_{\Omega} (|u|u_i - |v|v_i) w_i dx \quad (2.5) \\ &= - \int_{\Omega} \lambda \nabla u_i \nabla w_i dx + \int_{\Omega} \lambda_2 \nabla v_i \nabla w_i dx - a \|w\|^2 - b \int_{\Omega} (|u|u_i - |v|v_i) w_i dx \end{aligned}$$

Since

$$\begin{aligned} &(|u|u_i - |v|v_i) w_i \\ &= \frac{1}{2} |u| (u_i - v_i + v_i) w_i - \frac{1}{2} |v| v_i w_i + \frac{1}{2} |u| u_i w_i + \frac{1}{2} |v| w_i (u_i - v_i - u_i) \quad (2.6) \\ &= \frac{1}{2} (|u| + |v|) w_i w_i dx + \frac{1}{2} (|u| - |v|)^2 (|u| + |v|) \end{aligned}$$

Combining (2.5) and (2.6), using the Cauchy-Schwarz inequality and dropping some negative items, we obtain

$$\frac{d}{dt} \|w\|^2 \leq \frac{\lambda^2}{2\lambda_2} \|\nabla u\|^2$$

Integrating from 0 to t , we obtain

$$\|w\|^2 \leq \frac{\lambda^2}{2\lambda_2} \int_0^t \|\nabla u\|^2 d\eta \quad (2.7)$$

Our next step is to bound $\int_0^t \|\nabla u\|^2 d\eta$. Multiplying (2.1)₁ by u_i and integrating over Ω , we see that

$$\frac{d}{dt} \|u\|^2 + 2\lambda_1 \|\nabla u\|^2 \leq 0$$

Integrating from 0 to t , we obtain

$$\|u\|^2 + 2\lambda_1 \int_0^t \|\nabla u\|^2 d\eta \leq \|f\|^2 \quad (2.8)$$

thus

$$\int_0^t \|\nabla u\|^2 d\eta \leq \frac{\|f\|^2}{2\lambda_1} \quad (2.9)$$

Combining (2.7) and (2.9), we obtain

$$\|w\|^2 \leq \frac{\lambda^2}{4\lambda_1\lambda_2} \|f\|^2 \quad (2.10)$$

Inequality (2.10) shows the continuous dependence on λ . However, the convergence result can't follow from (2.10) as $\lambda_1 \rightarrow 0, \lambda_2 = 0$.

3. CONVERGENCE AS $\lambda_1 \rightarrow 0, \lambda_2 = 0$

Let (u_i, p) be a solution of (2.1) with $\lambda_1 \rightarrow 0$, (v_i, p) be a solution of (2.1) with $\lambda_1 \rightarrow 0$, w_i, π are defined the same as in section 2.

$$\begin{aligned} \frac{\partial w_i}{\partial t} &= \lambda_1 \Delta u_i - a w_i - b(|u|u_i - |v|v_i) - \pi_{,i} \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial w_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ w_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ w_i(x, 0) &= 0, \quad x \in \Omega \end{aligned} \quad (3.1)$$

Multiplying (3.1)₁ by w_i and integrating over Ω , we find

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \|w\|^2 \\ &= -\lambda_1 \int_{\Omega} \nabla u_i \nabla w_i dx - a \|w\|^2 - b \int_{\Omega} (|u|u_i - |v|v_i) w_i dx \\ &= -\lambda_1 \int_{\Omega} \nabla u_i \nabla u_i dx + \lambda_1 \int_{\Omega} \nabla u_i \nabla v_i dx - a \|w\|^2 - b \int_{\Omega} (|u|u_i - |v|v_i) w_i dx \\ &\leq \frac{\lambda_1}{4} \int_{\Omega} \nabla v_i \nabla v_i dx - a \|w\|^2. \end{aligned} \quad (3.2)$$

The next step is to bound $\int_{\Omega} v_{i,j} v_{i,j} dx$. We know

$$\int_{\Omega} v_{i,j} v_{i,j} dx = \int_{\Omega} v_{i,j} (v_{i,j} - v_{j,i}) dx. \quad (3.3)$$

Using (2.2)₁ with $\lambda_2 = 0$, we get

$$\begin{aligned}
& \int_0^t \int_{\Omega} v_{i,j}(v_{i,j} - v_{j,i}) ds d\eta \\
&= \frac{1}{a} \int_0^t \int_{\Omega} (v_{i,j} - v_{j,i})(-v_{i,jt} - b(|v|v_{i,j} - q_{i,j})) dx d\eta \\
&= -\frac{1}{a} \int_0^t \int_{\Omega} (v_{i,j} - v_{j,i})v_{i,jt} ds d\eta - \frac{b}{a} \int_0^t \int_{\Omega} (v_{i,j} - v_{j,i}) \\
&\quad \times \left(\frac{v_k v_{k,j}}{|v|} v_i + |v|v_{i,j} \right) ds d\eta + \frac{1}{a} \int_0^t \int_{\Omega} v_{i,i} q_{j,j} ds d\eta \\
&\quad - \frac{1}{a} \int_0^t \int_{\Omega} v_{j,j} q_{i,i} ds d\eta - \frac{1}{a} \int_0^t \int_{\partial\Omega} v_{i,j} q_{j,i} n_i ds d\eta + \frac{1}{a} \int_0^t \int_{\partial\Omega} v_{j,i} q_{i,j} n_j ds d\eta \\
&= -\frac{1}{2a} \int_{\Omega} v_{i,j} v_{i,j} dx|_{\eta=t} + \frac{1}{2a} \int_{\Omega} f_{i,j} f_{i,j} dx \\
&\quad - \frac{b}{a} \int_0^t \int_{\Omega} \frac{v_k v_{k,j} v_i v_{i,j}}{|v|} ds d\eta - \frac{b}{a} \int_0^t \int_{\Omega} v_{i,j} |v| v_{i,j} ds d\eta
\end{aligned} \tag{3.4}$$

thus

$$\int_0^t \int_{\Omega} v_{i,j} v_{i,j} ds d\eta \leq \frac{1}{2a} \int_{\Omega} f_{i,j} f_{i,j} dx \tag{3.5}$$

Combining (3.2), (3.3) and (3.5), we get

$$\|w\|^2 \leq \frac{\lambda_1}{8a} \int_{\Omega} f_{i,j} f_{i,j} ds d\eta$$

This inequality demonstrates the convergence $u \rightarrow v$ when $\lambda_1 \rightarrow 0$, $\lambda_2 = 0$.

4. CONTINUOUS DEPENDENCE FOR THE FORCHHEIMER COEFFICIENT B

To study continuous dependence on b , we let (u_i, p) and (v_i, q) solve the following boundary initial-value problem for different coefficients b_1 and b_2 .

$$\begin{aligned}
\frac{\partial u_i}{\partial t} &= \lambda \Delta u_i - a u_i - b_1 |u| u_i - p_{,i} \quad \text{in } \Omega \times \{t > 0\} \\
\frac{\partial u_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\
u_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\
u_i(x, 0) &= f_i(x), \quad x \in \Omega
\end{aligned} \tag{4.1}$$

and

$$\begin{aligned}
\frac{\partial v_i}{\partial t} &= \lambda \Delta v_i - a v_i - b_2 |v| v_i - q_{,i} \quad \text{in } \Omega \times \{t > 0\} \\
\frac{\partial v_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\
v_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\
v_i(x, 0) &= f_i(x), \quad x \in \Omega
\end{aligned} \tag{4.2}$$

We define the difference variables

$$w_i = u_i - v_i, \quad \pi = p - q, \quad b = b_1 - b_2. \tag{4.3}$$

Then (w_i, π) satisfy the boundary initial-value problem

$$\begin{aligned} \frac{\partial w_i}{\partial t} &= \lambda \Delta w_i - a w_i - (b_1 |u| u_i - b_2 |v| v_i) - \pi_{,i} \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial w_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ w_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ w_i(x, 0) &= 0, \quad x \in \Omega \end{aligned} \quad (4.4)$$

Multiplying (4.4)₁ by w_i and integrating over Ω , we get

$$\frac{1}{2} \frac{d}{dt} \|w\|^2 = -\lambda \int_{\Omega} |\nabla w|^2 dx - a \|w\|^2 - \int_{\Omega} (b_1 |u| u_i - b_2 |v| v_i) w_i dx \quad (4.5)$$

For we have

$$b_1 |u| u_i - b_2 |v| v_i = \frac{b}{2} (|u| u_i + |v| v_i) + \tilde{b} (|u| u_i - |v| v_i) \quad (4.6)$$

where $\tilde{b} = \frac{b_1 + b_2}{2}$. Combining (4.5), (4.6) and (2.6), we obtain

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|w\|^2 \\ &= -\lambda \int_{\Omega} |\nabla w|^2 dx - a \|w\|^2 - \frac{b}{2} \int_{\Omega} (|u| u_i + |v| v_i) w_i dx - \tilde{b} \int_{\Omega} (|u| u_i - |v| v_i) w_i dx \\ &\leq -a \|w\|^2 - \frac{b}{2} \int_{\Omega} (|u| u_i + |v| v_i) w_i dx - \frac{\tilde{b}}{2} \int_{\Omega} (|u| + |v|) w_i w_i dx \end{aligned} \quad (4.7)$$

We then use the Cauchy-Schwarz and arithmetic geometric mean inequalities as follows

$$\frac{b}{2} \left| \int_{\Omega} (|u| u_i + |v| v_i) w_i dx \right| \leq \frac{b^2}{8\tilde{b}} \int_{\Omega} (|u|^3 + |v|^3) dx + \frac{1}{2} \tilde{b} \int_{\Omega} (|u| + |v|) w_i w_i dx \quad (4.8)$$

We now employ (4.8) in (4.7), after an integration, that

$$\frac{1}{2} \|w\|^2 + a \int_0^t \|w\|^2 d\eta \leq \frac{b^2}{8\tilde{b}} \int_0^t \int_{\Omega} (|u|^3 + |v|^3) ds d\eta \quad (4.9)$$

From (4.1)₁, one deduce that

$$\frac{1}{2} \|u\|^2 + a \int_0^t \|u\|^2 d\eta + b_1 \int_0^t \int_{\Omega} |u|^3 ds d\eta + \lambda \int_0^t \int_{\Omega} u_{i,j} u_{i,j} ds d\eta = \frac{1}{2} \|f\|^2 \quad (4.10)$$

and so

$$\int_0^t \int_{\Omega} |u|^3 ds d\eta \leq \frac{1}{2b_1} \|f\|^2 \quad (4.11)$$

Similarly, from (4.2)₁, we can also get

$$\int_0^t \int_{\Omega} |v|^3 ds d\eta \leq \frac{1}{2b_1} \|f\|^2 \quad (4.12)$$

Inserting (4.11), (4.12) in (4.10), we find

$$\|w\|^2 + 2a \int_0^t \|w\|^2 d\eta \leq \frac{b^2}{4b_1 b_2} \|f\|^2 \quad (4.13)$$

This inequality establish continuous dependence on b , we note, however, that convergence as $b_1 \rightarrow 0$, $b_2 = 0$ is not established from (4.13).

5. CONVERGENCE AS THE FORCHHEIMER COEFFICIENT $b_1 \rightarrow 0$ AND $b_2 = 0$

Now, let (u_i, p) be the solution of (4.1), and (v_i, q) be the solution of (4.2) with $b_2 = 0$. The object of this section is to demonstrate convergence of the solution u_i to the solution v_i as $b_1 \rightarrow 0$. We also define the variables w_i and π by

$$w_i = u_i - v_i, \quad \pi = p - q \quad (5.1)$$

and then (w_i, π) satisfy the boundary initial-value problems

$$\begin{aligned} \frac{\partial w_i}{\partial t} &= \lambda \Delta w_i - a w_i - b_1 |u| u_i - \pi_i \quad \text{in } \Omega \times \{t > 0\} \\ \frac{\partial w_i}{\partial x_i} &= 0 \quad \text{in } \Omega \times \{t > 0\} \\ w_i &= 0 \quad \text{on } \partial\Omega \times \{t > 0\} \\ w_i(x, 0) &= 0, \quad x \in \Omega \end{aligned} \quad (5.2)$$

Multiplying by w_i and integrating over Ω , we obtain

$$\frac{1}{2} \frac{d}{dt} \|w\|^2 = -\lambda \|\nabla w\|^2 - a \|w\|^2 - b_1 \int_{\Omega} |u| u_i w_i dx \quad (5.3)$$

Using the Hölder inequality, we get

$$\frac{d}{dt} \|w\|^2 \leq 2b_1 \left(\int_{\Omega} |u|^3 dx \right)^{2/3} \left(\int_{\Omega} |w|^3 dx \right)^{1/3} - 2\lambda \|\nabla w\|^2 - 2a \|w\|^2 \quad (5.4)$$

For a function F such that $F = 0$ on $\partial\Omega$ (see for example [2]), we have the Sobolev inequality

$$\int_{\Omega} |F|^4 dx \leq c_1 \left(\int_{\Omega} |F|^2 dx \right)^{1/2} \left(\int_{\Omega} F_{i,j} F_{i,j} dx \right)^{3/2}$$

Then, we use the Cauchy-Schwarz inequality, to get

$$\begin{aligned} \int_{\Omega} |w|^3 dx &\leq \left(\int_{\Omega} |w|^2 dx \right)^{1/2} \left(\int_{\Omega} |w|^4 dx \right)^{1/2} \\ &\leq c_1 \left(\int_{\Omega} w_i w_i dx \right)^{3/4} \left(\int_{\Omega} w_{i,j} w_{i,j} dx \right)^{3/4} \end{aligned} \quad (5.5)$$

Similarly,

$$\int_{\Omega} |u|^3 dx \leq c_1 \left(\int_{\Omega} u_i u_i dx \right)^{3/4} \left(\int_{\Omega} u_{i,j} u_{i,j} dx \right)^{3/4} \quad (5.6)$$

In view of (5.4) and (5.5), (5.3) can be rewritten as

$$\begin{aligned}
\|w\|^2 &\leq 2b_1c_1 \int_0^t \left[\left(\int_{\Omega} w_i w_i dx \right)^{1/4} \left(\int_{\Omega} w_{i,j} w_{i,j} dx \right)^{1/4} \left(\int_{\Omega} u_i u_i dx \right)^{1/2} \right. \\
&\quad \left. \times \left(\int_{\Omega} u_{i,j} u_{i,j} dx \right)^{1/2} \right] d\eta - 2\lambda \int_0^t \|\nabla w\|^2 d\eta - 2a \int_0^t w^2 ds d\eta \\
&\leq 2\lambda \int_0^t \|\nabla w\|^2 d\eta - 2a \int_0^t \|w\|^2 d\eta - 2b_1c_1 \int_0^t \left[\left(\varepsilon_1 \int_{\Omega} w_i w_i dx \right)^{1/4} \right. \\
&\quad \left. \times \left(\varepsilon_2 \int_{\Omega} w_{i,j} w_{i,j} dx \right)^{1/4} \left(\max_{\Omega} \int_{\Omega} u_i u_i dx \cdot \int_{\Omega} (\varepsilon_1 \varepsilon_2)^{-1/2} u_{i,j} u_{i,j} dx \right)^{1/2} \right] d\eta \\
&\leq \frac{1}{4} \varepsilon_1 \int_0^t \int_{\Omega} w_i w_i ds d\eta + \frac{1}{4} \varepsilon_2 \int_0^t \int_{\Omega} w_{i,j} w_{i,j} ds d\eta \\
&\quad + \frac{4}{2} (b_1c_1)^2 \cdot (\varepsilon_1 \varepsilon_2)^{-1/2} \int_0^t \int_{\Omega} u_{i,j} u_{i,j} ds d\eta \\
&\quad - 2a \max_{\Omega} \int_{\Omega} u_i u_i dx \int_0^t \int_{\Omega} w^2 ds d\eta - 2\lambda \int_0^t \|\nabla w\|^2 d\eta - 2a \int_0^t \|w\|^2 d\eta
\end{aligned}$$

If we choose $\varepsilon_1 = 8a$, $\varepsilon_2 = 8\lambda$, the above expression can be rewritten as

$$\|w\|^2 \leq \frac{b_1^2 c_1^2}{4(a\lambda)^{1/2}} \max_{\Omega} \int_{\Omega} u_i u_i dx \cdot \int_0^t \int_{\Omega} u_{i,j} u_{i,j} ds d\eta \quad (5.7)$$

From (4.10), we have

$$\max_{\Omega} \int_{\Omega} u_i u_i dx \leq \|f\|^2, \quad \int_0^t \int_{\Omega} u_{i,j} u_{i,j} ds d\eta \leq \frac{1}{2\lambda} \|f\|^2;$$

therefore, from (5.7), we have

$$\|w\|^2 \leq \frac{(b_1c_1)^2}{8a^{1/2}\lambda^{3/2}} \|f\|^4,$$

which shows the desired result.

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