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# MULTIPLE SIGN-CHANGING SOLUTIONS FOR SOME M-POINT BOUNDARY-VALUE PROBLEMS 

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#### Abstract

In this paper, we show existence results for multiple sign-changing solutions for m-point boundary-value problems. We use fixed point index and Leray-Schauder degree methods.


## 1. Introduction

In this paper, we consider the second-order multi-point boundary-value problem

$$
\begin{align*}
& y^{\prime \prime}(t)+f(y)=0, \quad 0 \leq t \leq 1 \\
& y(0)=0, \quad y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right) \tag{1.1}
\end{align*}
$$

where $0<\alpha_{i}, i=1,2, \ldots, m-2,0<\eta_{1}<\eta_{2}<\cdots<\eta_{m-2}<1, f \in C(\mathbb{R}, \mathbb{R})$.
The multi-point boundary-value problems for ordinary differential equations arise in different areas of applied mathematics and physics. For examples, the vibrations of a guy wire of uniform cross-section and composed of $N$ parts of different densities can be set up as a multi-point boundary-value problem (see [11), many problems in the theory of elastic stability can be handled as multi-point problems (see [13]). Recently, there is much attention focused on the existence of nontrivial or positive solutions of the nonlinear multi-point boundary-value problems(see [3, 4, 5, 7, 9, 10, 12, 14, 15, 16, 17] and the references therein). For example, Ruyun Ma 9] considered the m-point boundary-value problem

$$
\begin{gather*}
u^{\prime \prime}(t)+a(t) f(u)=0, \quad t \in(0,1) \\
u^{\prime}(0)=\sum_{i=1}^{m-2} b_{i} u^{\prime}\left(\xi_{i}\right), \quad u(1)=\sum_{i=1}^{m-2} a_{i} u\left(\xi_{i}\right), \tag{1.2}
\end{gather*}
$$

where $f \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right), \xi_{i} \in(0,1)$ with $0<\xi_{1}<\xi_{2}<\cdots<\xi_{m-2}<1, a_{i}, b_{i} \in \mathbb{R}^{+}$ with $0<\sum_{i=1}^{m-2} a_{i}<1$, and $0<\sum_{i=1}^{m-2} b_{i}<1$. Set

$$
f_{0}=\lim _{u \rightarrow 0^{+}} \frac{f(u)}{u}, \quad f_{\infty}=\lim _{u \rightarrow+\infty} \frac{f(u)}{u} .
$$

[^0]Then $f_{0}=0$ and $f_{\infty}=\infty$ correspond to the super-linear case, and $f_{0}=\infty$ and $f_{\infty}=0$ correspond to the sub-linear case. By applying the fixed point theorem in cones, Ruyun Ma 9 showed that the m-point boundary value problem (1.2) has at least one positive solution if $f$ is either super-linear or sub-linear.

In this paper, we shall study the cases $f_{0}, f_{\infty} \notin\{0,+\infty\}$. In these cases, the m-point boundary-value problem 1.1 may have sign-changing solutions. Quite recently, the existence and qualitative properties of sign-changing solutions for elliptic boundary-value problems have been extensively studied. To the author's knowledge, however, there were fewer papers considered the sign-changing solutions for multi-point boundary value problems. The purpose of this paper is to give some existence results for multiple sign-changing solution for m-point boundary value problem 1.1). We shall follow the idea employed in 8 by Liu. To show the main result in this paper we need to study the the spectrum properties of the linear operator related the m-point boundary-value problem (1.1). Gupta and Sergej Trofimchuk [4] studied the problem of existence of solutions for the three-point boundary-value problem

$$
\begin{gather*}
x^{\prime \prime}(t)=f\left(t, x(t), x^{\prime}(t)\right), \quad t \in(0,1) \\
x(0)=0, \quad x(1)=\alpha x(\eta) \tag{1.3}
\end{gather*}
$$

where $\alpha \in \mathbb{R}, \alpha \leq 1$ and $\eta \in(0,1)$ are given. Using the spectrum radius of some related linear operators, the authors proved some existence results for nontrivial solutions of the three-point boundary-value problem (1.3).

We shall organize this paper as follows. In $\S 2$ some preliminary results are given including the study of the eigenvalues of the linear operator $A^{\prime}(\theta)$ and $A^{\prime}(\infty)$. In $\S 3$ by using the fixed point index and Leray-Shauder degree method, we will prove the main result.

## 2. Preliminary Lemmas

From [1, Theorem 2.3.1], we have the following definition. Let $X$ be a retract of real Banach space $E, U$ be a relatively bounded open subset of $X, A: D \mapsto X$ be completely continuous operator. The integer $i(A, U, X)$ be defined by

$$
i(A, U, X)=\operatorname{deg}\left(I-A \cdot r, B(\theta, R) \cap r^{-1}(U), \theta\right)
$$

where $r: E \mapsto X$ is an arbitrary retraction and $R>0$ such that $B(\theta, R) \supset U$. Then the integer $i(A, U, X)$ be called the fixed point index of $A$ on $U$ with respect to $X$.

Set

$$
\beta_{0}=\lim _{x \rightarrow 0} \frac{f(x)}{x}, \quad \beta_{1}=\lim _{|x| \rightarrow \infty} \frac{f(x)}{x}
$$

Let us list some conditions to be used in this paper.
(H0) Assume that the sequence of positive solutions of the equation

$$
\sin \sqrt{x}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{x}
$$

is $\lambda_{1}<\lambda_{2}<\cdots<\lambda_{n}<\lambda_{n+1}<\ldots$
(H1) $0<\sum_{i=1}^{m-2} \alpha_{i}<1, f \in C(\mathbb{R}, \mathbb{R}), f(0)=0, x f(x)>0$ for all $x \in \mathbb{R} \backslash\{0\}$.
(H2) There exist positive integers $n_{0}$ and $n_{1}$ such that

$$
\lambda_{2 n_{0}}<\beta_{0}<\lambda_{2 n_{0}+1}, \quad \lambda_{2 n_{1}}<\beta_{1}<\lambda_{2 n_{1}+1}
$$

(H3) There exists $C_{0}>0$ such that

$$
|f(x)|<\frac{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} C_{0}
$$

for all $x$ with $|x| \leq C_{0}$.
The main result of this paper is the following.
Theorem 2.1. Suppose that (H0)-(H3) hold. Then the m-point boundary-value problem 1.1 has at least two sign-changing solutions. Moreover, the m-point boundary-value problem 1.1 also has at least two positive solutions and two negative solutions.

Before giving the proof of Theorem 2.1, we list some preliminary lemmas. Let

$$
\begin{gathered}
E=\left\{x \in C^{1}[0,1]: x(0)=0, x(1)=\sum_{i=1}^{m-2} \alpha_{i} x\left(\eta_{i}\right)\right\} \\
P=\{x \in E: x(t) \geq 0 \text { for } t \in[0,1]\}
\end{gathered}
$$

For $x \in E$, let $\|x\|=\|x\|_{0}+\left\|x^{\prime}\right\|_{0}$, where $\|x\|_{0}=\max _{t \in[0,1]}|x(t)|$ and $\left\|x^{\prime}\right\|_{0}=$ $\max _{t \in[0,1]}\left|x^{\prime}(t)\right|$. It is easy to show that $E$ is a Banach space with the norm $\|\cdot\|$ and $P$ is a cone of $E$. Let the operators $K, F$ and $A$ be defined by

$$
\begin{align*}
(K x)(t)= & \frac{t}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \int_{0}^{1}(1-s) x(s) d s-\int_{0}^{t}(t-s) x(s) d s \\
& -\frac{t}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right) x(s) d s, \quad t \in[0,1], x \in E \tag{2.1}
\end{align*}
$$

$(F x)(t)=f(x(t))$ for $t \in[0,1], x \in E$ and $A=K F$.
From [1, Lemma 2.3.1], we get the following Lemma.
Lemma 2.2. Let $\theta \in \Omega$ and $A: P \cap \bar{\Omega} \mapsto P$ be condensing. Suppose that

$$
A x \neq \mu x, \quad \forall x \in P \cap \partial \Omega, \mu \geq 1
$$

Then $i(A, P \cap \Omega, P)=1$.
From [2, Corollary 2, p.p.146], we have the following Lemma.
Lemma 2.3. Let $\Omega$ be a open set in $E$ and $\theta \in \Omega, A: \bar{\Omega} \mapsto E$ be completely continuous. Suppose that

$$
\|A x\| \leq\|x\|, \quad A x \neq x, \forall x \in \partial \Omega
$$

Then $\operatorname{deg}(I-A, \Omega, \theta)=1$.
Remark Obviously, Lemma 2.3 can also be directly obtained by the normality and homotopic invariance property of Leray-Schauder degree.

The following Lemma can be easily obtained.
Lemma 2.4. Suppose that $\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}<1$. If $u \in C[0,1]$, then $y \in C^{2}[0,1]$ is a solution the m-point boundary-value problem

$$
\begin{aligned}
& y^{\prime \prime}(t)+u(t)=0, \quad 0 \leq t \leq 1 \\
& y(0)=0, \quad y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right)
\end{aligned}
$$

if and only if $y \in C[0,1]$ is a solution of the integral equation $y(t)=(K u)(t), t \in$ $[0,1]$.
Remark By Lemma 2.4 we can easily show that $A: E \mapsto E$ is a completely continuous operator.
Lemma 2.5. Suppose that (H1) and (H2) hold. Then the operator $A$ is Fréchet differentiable at $\theta$ and $\infty$. Moreover, $A^{\prime}(\theta)=\beta_{0} K$, and $A^{\prime}(\infty)=\beta_{1} K$.
Proof. For any $\varepsilon>0$, by (H2) there exists $\delta>0$ such that for any $0<|x|<\delta$,

$$
\left|\frac{f(x)}{x}-\beta_{0}\right|<\varepsilon
$$

that is $\left|f(x)-\beta_{0} x\right|<\varepsilon|x|$, for all $0 \leq|x|<\delta$. Then, for any $x \in E$ with $\|x\|<\delta$, we have

$$
\begin{aligned}
\mid & \left(A x-A \theta-\beta_{0} K x\right)(t) \mid \\
= & \left|\left(K\left(F x-\beta_{0} x\right)\right)(t)\right| \\
\leq & \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \int_{0}^{1}(1-s) \max _{s \in[0,1]}\left|f(x(s))-\beta_{0} x(s)\right| d s \\
& +\int_{0}^{1}(1-s) \max _{s \in[0,1]}\left|f(x(s))-\beta_{0} x(s)\right| d s \\
& +\frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right) \max _{s \in[0,1]}\left|f(x(s))-\beta_{0} x(s)\right| d s \\
\leq & {\left[\frac{1}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}+\frac{1}{2}+\frac{\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}^{2}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\right]\|x\|_{0} \varepsilon } \\
\leq & \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\|x\| \varepsilon, t \in[0,1] .
\end{aligned}
$$

This implies

$$
\begin{equation*}
\left\|A x-A \theta-\beta_{0} K x\right\|_{0} \leq \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\|x\| \varepsilon, \quad x \in E,\|x\|<\delta \tag{2.2}
\end{equation*}
$$

Similarly, we can show that for any $x \in E,\|x\|<\delta$,

$$
\left|\left(A x-A \theta-\beta_{0} K x\right)^{\prime}(t)\right| \leq \frac{3-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\|x\| \varepsilon, \quad t \in[0,1]
$$

and so

$$
\begin{equation*}
\left\|\left(A x-A \theta-\beta_{0} K x\right)^{\prime}\right\|_{0} \leq \frac{3-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\|x\| \varepsilon, x \in E,\|x\|<\delta \tag{2.3}
\end{equation*}
$$

By (2.2) and (2.3), we have

$$
\begin{aligned}
\left\|A x-A \theta-\beta_{0} K x\right\| & =\left\|A x-A \theta-\beta_{0} K x\right\|_{0}+\left\|\left(A x-A \theta-\beta_{0} K x\right)^{\prime}\right\|_{0} \\
& \leq \frac{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\|x\| \varepsilon
\end{aligned}
$$

Consequently,

$$
\lim _{\|x\| \rightarrow 0} \frac{\left\|A x-A \theta-\beta_{0} K x\right\|}{\|x\|}=0
$$

This means that $A$ is Fréchet differentiable at $\theta$, and $A^{\prime}(\theta)=\beta_{0} K$.
For each $\varepsilon>0$, by (H2), there exists $R>0$ such that

$$
\left|f(x)-\beta_{1} x\right|<\varepsilon|x|
$$

for $|x|>R$. Let $b=\max _{|x| \leq R}\left|f(x)-\beta_{1} x\right|$. Then we have for any $x \in \mathbb{R}$,

$$
\left|f(x)-\beta_{1} x\right| \leq \varepsilon|x|+b
$$

Consequently,

$$
\begin{aligned}
\mid & \left(A x-\beta_{1} K x\right)(t) \mid \\
= & \left|\left(K\left(F x-\beta_{1} x\right)\right)(t)\right| \\
\leq & \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \int_{0}^{1}(1-s) \max _{s \in[0,1]}\left|f(x(s))-\beta_{1} x(s)\right| d s \\
& +\int_{0}^{1}(1-s) \max _{s \in[0,1]}\left|f(x(s))-\beta_{1} x(s)\right| d s \\
& +\frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right) \max _{s \in[0,1]}\left|f(x(s))-\beta_{1} x(s)\right| d s \\
\leq & {\left[\frac{1}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}+\frac{1}{2}+\frac{\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}^{2}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\right]\left(\varepsilon\|x\|_{0}+b\right) } \\
\leq & \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}(\varepsilon\|x\|+b), \quad t \in[0,1] .
\end{aligned}
$$

This implies

$$
\begin{equation*}
\left\|A x-\beta_{1} K x\right\|_{0} \leq \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}(\varepsilon\|x\|+b), \quad x \in E \tag{2.4}
\end{equation*}
$$

Similarly, we can show that

$$
\begin{equation*}
\left\|\left(A x-\beta_{1} K x\right)^{\prime}\right\|_{0} \leq \frac{3-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}(\varepsilon\|x\|+b), \quad x \in E \tag{2.5}
\end{equation*}
$$

By (2.4) and 2.5), we have

$$
\begin{aligned}
\left\|A x-\beta_{1} K x\right\| & =\left\|A x-\beta_{1} K x\right\|_{0}+\left\|\left(A x-\beta_{1} K x\right)^{\prime}\right\|_{0} \\
& \leq \frac{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}(\varepsilon\|x\|+b)
\end{aligned}
$$

Consequently,

$$
\lim _{\|x\| \rightarrow \infty} \frac{\left\|A x-\beta_{1} K x\right\|}{\|x\|}=0 .
$$

This means that $A$ is Fréchet differentiable at $\infty$, and $A^{\prime}(\infty)=\beta_{1} K$. The proof is complete.

Lemma 2.6. Suppose that (H0) and (H1) hold. Let $\beta$ be a positive number. Then the sequence of positive eigenvalues of the operator $\beta K$ is

$$
\frac{\beta}{\lambda_{1}}>\frac{\beta}{\lambda_{2}}>\cdots>\frac{\beta}{\lambda_{n}} \ldots
$$

Moreover, the positive eigenvalues $\frac{\beta}{\lambda_{n}}(n=1,2, \ldots)$ have algebraic multiplicity one.

Proof. Let $\bar{\lambda}$ be a positive eigenvalue of the linear operator $\beta K$, and $y \in E \backslash\{\theta\}$ be an eigenfunction corresponding to the eigenvalue $\bar{\lambda}$. By Lemma 2.4, we have

$$
\begin{gather*}
y^{\prime \prime}(t)+\frac{\beta}{\bar{\lambda}} y(t)=0,0 \leq t \leq 1 \\
y(0)=0, \quad y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right) \tag{2.6}
\end{gather*}
$$

The auxiliary equation of the differential equation has roots $\pm \sqrt{\frac{\beta}{\lambda}} i$. Thus the general solution of 2.6 is of the form

$$
y(t)=C_{1} \cos t \sqrt{\frac{\beta}{\bar{\lambda}}}+C_{2} \sin t \sqrt{\frac{\beta}{\bar{\lambda}}}, \quad t \in[0,1] .
$$

Applying the condition $y(0)=0$, we obtain that $C_{1}=0$, and so the general solution can be reduce to

$$
y(t)=C_{2} \sin t \sqrt{\frac{\beta}{\bar{\lambda}}}, \quad t \in[0,1]
$$

Applying the second condition $y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right)$, we obtain that

$$
\sin \sqrt{\frac{\beta}{\bar{\lambda}}}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\frac{\beta}{\bar{\lambda}}}
$$

Since the positive solutions of the equation $\sin \sqrt{x}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{x}$ are $0<$ $\lambda_{1}<\lambda_{2}<\ldots$, then $\bar{\lambda}$ is one of the values

$$
\frac{\beta}{\lambda_{1}}>\frac{\beta}{\lambda_{2}}>\cdots>\frac{\beta}{\lambda_{n}} \ldots
$$

and the eigenfunction corresponding to the eigenvalue $\frac{\beta}{\lambda_{n}}$ is

$$
y_{n}(t)=C \sin t \sqrt{\lambda_{n}}, \quad t \in[0,1],
$$

where $C$ is a nonzero constant. By ordinary method, we can show that any two eigenfunctions corresponding to the same eigenvalue $\frac{\beta}{\lambda_{n}}$ are merely nonzero constant multiples of each other. Consequently,

$$
\begin{equation*}
\operatorname{dim} \operatorname{ker}\left(\frac{\beta}{\lambda_{n}} I-\beta K\right)=\operatorname{dim} \operatorname{ker}\left(I-\lambda_{n} K\right)=1 \tag{2.7}
\end{equation*}
$$

Now we show that

$$
\begin{equation*}
\operatorname{ker}\left(I-\lambda_{n} K\right)=\operatorname{ker}\left(I-\lambda_{n} K\right)^{2} \tag{2.8}
\end{equation*}
$$

Obviously, we need to show only that

$$
\operatorname{ker}\left(I-\lambda_{n} K\right)^{2} \subset \operatorname{ker}\left(I-\lambda_{n} K\right)
$$

For any $y \in \operatorname{ker}\left(I-\lambda_{n} K\right)^{2},\left(I-\lambda_{n} K\right) y$ is an eigenfunction of linear operator $\beta K$ corresponding to the eigenvalue $\frac{\beta}{\lambda_{n}}$ if $\left(I-\lambda_{n} K\right) y \neq \theta$. Then there exists nonzero constant $\gamma$ such that

$$
\left(I-\lambda_{n} K\right) y=\gamma \sin t \sqrt{\lambda_{n}}, \quad t \in[0,1] .
$$

By direct computation, we have

$$
\begin{gather*}
y^{\prime \prime}(t)+\lambda_{n} y=-\lambda_{n} \gamma \sin t \sqrt{\lambda_{n}}, \quad t \in[0,1] \\
y(0)=0, \quad y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right) \tag{2.9}
\end{gather*}
$$

It is easy to see that the general solutions of 2.9 is of the form

$$
\begin{aligned}
y(t)= & C_{1} \cos t \sqrt{\lambda_{n}}+C_{2} \sin t \sqrt{\lambda_{n}}+\left(\frac{\gamma t \sqrt{\lambda_{n}}}{2}-\frac{\gamma}{4} \sin 2 t \sqrt{\lambda_{n}}\right) \cos t \sqrt{\lambda_{n}} \\
& +\frac{\gamma}{4} \cos 2 t \sqrt{\lambda_{n}} \cdot \sin t \sqrt{\lambda_{n}}, \quad t \in[0,1]
\end{aligned}
$$

where $C_{1}, C_{2}$ are two nonzero constants. Applying the condition $y(0)=0$, we obtain that $C_{1}=0$. Since $\sin \sqrt{\lambda_{n}}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\lambda_{n}}$, then we have

$$
\begin{align*}
y(1)= & C_{2} \sin \sqrt{\lambda_{n}}+\left(\frac{\gamma \sqrt{\lambda_{n}}}{2}-\frac{\gamma}{4} \sin 2 \sqrt{\lambda_{n}}\right) \cos \sqrt{\lambda_{n}}+\frac{\gamma}{4} \cos 2 \sqrt{\lambda_{n}} \cdot \sin \sqrt{\lambda_{n}} \\
= & \sum_{i=1}^{m-2} \alpha_{i} C_{2} \sin \eta_{i} \sqrt{\lambda_{n}}+\frac{\gamma \sqrt{\lambda_{n}}}{2} \cos \sqrt{\lambda_{n}}-\frac{\gamma}{2} \sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\lambda_{n}} \cos ^{2} \sqrt{\lambda_{n}} \\
& +\frac{\gamma}{4} \sum_{i=1}^{m-2} \alpha_{i} \cos 2 \sqrt{\lambda_{n}} \sin \eta_{i} \sqrt{\lambda_{n}}, \tag{2.10}
\end{align*}
$$

and

$$
\begin{align*}
\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right)= & \sum_{i=1}^{m-2} \alpha_{i} C_{2} \sin \eta_{i} \sqrt{\lambda_{n}}+\sum_{i=1}^{m-2}\left(\frac{\gamma \alpha_{i} \eta_{i} \sqrt{\lambda_{n}}}{2}-\frac{\gamma \alpha_{i}}{4} \sin 2 \eta_{i} \sqrt{\lambda_{n}}\right) \cos \eta_{i} \sqrt{\lambda_{n}} \\
& +\sum_{i=1}^{m-2} \frac{\gamma \alpha_{i}}{4} \cos 2 \eta_{i} \sqrt{\lambda_{n}} \cdot \sin \eta_{i} \sqrt{\lambda_{n}} \tag{2.11}
\end{align*}
$$

Since $y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right)$, by 2.10 and 2.11, we have

$$
\cos \sqrt{\lambda_{n}}=\sum_{i=1}^{m-2} \alpha_{i} \eta_{i} \cos \eta_{i} \sqrt{\lambda_{n}}
$$

By the Schwarz inequality, we obtain

$$
\begin{aligned}
1-\sin ^{2} \sqrt{\lambda_{n}} & =\left(\sum_{i=1}^{m-2} \alpha_{i} \eta_{i} \cos \eta_{i} \sqrt{\lambda_{n}}\right)^{2} \\
& \leq\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2} \cos ^{2} \eta_{i} \sqrt{\lambda_{n}}\right) \\
& =\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2}\right)-\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2} \sin ^{2} \eta_{i} \sqrt{\lambda_{n}}\right)
\end{aligned}
$$

Applying the condition $\sin \sqrt{\lambda_{n}}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\lambda_{n}}$, we obtain

$$
\begin{aligned}
1 & \leq\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2}\right)+\left(\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\lambda_{n}}\right)^{2}-\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2} \sin ^{2} \eta_{i} \sqrt{\lambda_{n}}\right) \\
& =\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2}\right)+\left(1-\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2} \sin ^{2} \eta_{i} \sqrt{\lambda_{n}}\right) \\
& +\sum_{i \neq j}^{m} \alpha_{i} \alpha_{j} \sin \eta_{i} \sqrt{\lambda_{n}} \sin \eta_{j} \sqrt{\lambda_{n}} \\
& \leq\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2}\right)+\left(1-\left(\sum_{i=1}^{m-2} \eta_{i}^{2}\right)\right)\left(\sum_{i=1}^{m-2} \alpha_{i}^{2}\right)+\sum_{i \neq j} \alpha_{i} \alpha_{j} \\
& =\left(\sum_{i=1}^{m-2} \alpha_{i}\right)^{2},
\end{aligned}
$$

which is a contradiction of $\sum_{i=1}^{m-2} \alpha_{i}<1$. Thus, 2.8 holds. It follows from 2.7 and 2.8 that the algebraic multiplicity of the eigenvalue $\frac{\beta}{\lambda_{n}}$ is 1 . The proof is complete.

Lemma 2.7. Suppose that (H0) and (H1) hold and $y \in P \backslash\{\theta\}$ is a solution of the boundary-value problem (1.1). Then $y \in \stackrel{\circ}{P}$.

Proof. Since $y^{\prime \prime}(t)=-f(y(t)) \leq 0$ for $t \in[0,1]$, then $y$ is a concave function on $[0,1]$. For all $i \in\{1,2, \ldots, m-2\}$, we have from the concavity of $y$ that

$$
y(t) \leq \frac{y(1)-y\left(\eta_{i}\right)}{1-\eta_{i}}(t-1)+y(1), \quad t \in\left[0, \eta_{1}\right]
$$

that is $y(t)\left(1-\eta_{i}\right) \leq\left(y(1)-y\left(\eta_{i}\right)\right)(t-1)+y(1)\left(1-\eta_{i}\right), t \in\left[0, \eta_{1}\right]$. This together with the boundary condition $y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right)$ implies

$$
\begin{align*}
y(t) & \leq y(1) \frac{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right)+\left(1-\sum_{i=1}^{m-2} \alpha_{i}\right)(1-t)}{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right)} \\
& \leq y(1) \frac{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right)+\left(1-\sum_{i=1}^{m-2} \alpha_{i}\right)}{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right)}  \tag{2.12}\\
& =y(1) \frac{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right)}, \quad t \in\left[0, \eta_{1}\right] .
\end{align*}
$$

From the concavity of $y$ and this inequality, we have

$$
\begin{equation*}
y(t) \leq \frac{y\left(\eta_{1}\right)}{\eta_{1}} t \leq \frac{y\left(\eta_{1}\right)}{\eta_{1}} \leq y(1) \frac{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right) \eta_{1}}, t \in\left[\eta_{1}, 1\right] \tag{2.13}
\end{equation*}
$$

From this inequality and 2.12 it follows that

$$
y(1) \geq \frac{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right) \eta_{1}}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\|y\|_{0} .
$$

Since $y$ is a concave function on $[0,1]$, we have

$$
\begin{equation*}
y(t) \geq(y(1)-y(0)) t=y(1) t \geq \frac{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right) \eta_{1}}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\|y\|_{0} t, \quad t \in[0,1] \tag{2.14}
\end{equation*}
$$

Consequently,

$$
y^{\prime}(0)=\lim _{t \rightarrow 0} \frac{y(t)}{t} \geq \frac{\sum_{i=1}^{m-2} \alpha_{i}\left(1-\eta_{i}\right) \eta_{1}}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\|y\|_{0}>0
$$

Then there exist $\varepsilon>0$ and $\tau_{1}>0$ such that

$$
\begin{equation*}
y^{\prime}(t)>\tau_{1}, \forall t \in[0, \varepsilon] \tag{2.15}
\end{equation*}
$$

By 2.14, there exists $\tau_{2}>0$ such that

$$
\begin{equation*}
y(t)>\tau_{2}, \quad \forall t \in[\varepsilon, 1] \tag{2.16}
\end{equation*}
$$

Let $\tau=\min \left\{\tau_{1}, \tau_{2}\right\}$. Then by 2.15 and 2.16, we obtain $u(t) \geq 0, t \in[0,1]$ for any $u \in E$ with $\|u-y\|<\tau$. Therefore, $B(y, \tau) \subset P$ and $y \in \stackrel{\circ}{P}$, where $B(y, \tau)=\{x \in E:\|x-y\|<\tau\}$. The proof is complete.

By [1, Lemmas 2.3.7, 2.3.8], we have the following Lemma.
Lemma 2.8. Let $A: P \mapsto P$ be completely continuous, Suppose that $A$ is differentiable at $\theta$ and $\infty$ along $P$ and 1 is not an eigenvalue of $A_{+}^{\prime}(\theta)$ and $A_{+}^{\prime}(\infty)$ corresponding to a positive eigenfunction.
(1) If $A_{+}^{\prime}(\theta)$ has a positive eigenfunction corresponding to an eigenvalue greater than 1 , and $A \theta=\theta$. Then there exists $\tau>0$ such that $i(A, P \cap B(\theta, r), P)=$ 0 for any $0<r<\tau$.
(2) If $A_{+}^{\prime}(\infty)$ has a positive eigenfunction which corresponds to an eigenvalue greater than 1. Then there exists $\varsigma>0$ such that $i(A, P \cap B(\theta, R), P)=0$ for any $R>\varsigma$.

Lemma 2.9. Suppose that (H0)-(H3) hold. Then
(1) There exists $C_{0}>r_{0}>0$ such that for any $0<r \leq r_{0}$,

$$
i(A, P \cap B(\theta, r), P)=0, \quad i(A,-P \cap B(\theta, r),-P)=0
$$

(2) There exists $R_{0}>C_{0}$ such that for any $R \geq R_{0}$,

$$
i(A, P \cap B(\theta, R), P)=0, \quad i(A,-P \cap B(\theta, R),-P)=0
$$

Proof. We prove only conclusion (1). The same way, conclusion (2) can be proved. First we claim that $K(P) \subset P$ and $K(-P) \subset-P$. Let $x \in P$ be fixed and $y=K x$. Obviously, $y \in C^{1}[0,1]$. By direct computation, we have

$$
\begin{align*}
y(1) & =\frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\left(\sum_{i=1}^{m-2} \eta_{i} \int_{0}^{1}(1-s) x(s) d s-\sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right) x(s) d s\right) \\
& \geq \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(1-\eta_{i}\right) s x(s) d s \geq 0 \tag{2.17}
\end{align*}
$$

It follows from Lemma 2.4 that

$$
\begin{align*}
y^{\prime \prime}(t) & =-x(t) \leq 0, \quad \forall t \in[0,1] .  \tag{2.18}\\
y(0) & =0, \quad y(1)=\sum_{i=1}^{m-2} \alpha_{i} y\left(\eta_{i}\right) \tag{2.19}
\end{align*}
$$

By (2.18), we see that $y$ is a concave function on $[0,1]$. Then the boundary condition 2.17) and 2.19 mean that $y(t) \geq 0$ for $t \in[0,1]$. Therefore, $y \in P$, and so
$K(P) \subset P, K(-P) \subset(-P)$. Since $x f(x)>0$ for $x \in \mathbb{R} \backslash\{0\}$, then we see that $A(P) \subset P$ and $A(-P) \subset(-P)$.

It follows from Lemmas 2.5 and 2.6 that $A_{+}^{\prime}(\theta)=\beta_{0} K, \beta_{0} / \lambda_{1}(>1)$ is an eigenvalue of the linear operator $\beta_{0} K$ and the eigenfunction corresponding to $\frac{\beta_{0}}{\lambda_{1}}$ is

$$
y(t)=C \sin t \sqrt{\lambda_{1}}, \quad t \in[0,1]
$$

where $C$ is an arbitrary positive constant and $\lambda_{1}$ is the smallest positive solution of the equation $\sin \sqrt{x}=\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{x}$. Since

$$
\lim _{x \rightarrow 0} \frac{\sin \sqrt{x}-\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{x}}{\sqrt{x}}=1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}>0
$$

there exists $\delta_{0} \in(0,1)$ small enough such that

$$
\frac{\sin \sqrt{\delta_{0}}-\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\delta_{0}}}{\sqrt{\delta_{0}}} \geq \frac{1}{4}\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)>0
$$

On the other hand,

$$
\sin \sqrt{\pi^{2}}-\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \sqrt{\pi^{2}}=-\sum_{i=1}^{m-2} \alpha_{i} \sin \eta_{i} \pi<0
$$

Then, by the intermediate-value principle, $\lambda_{1} \in\left(\delta_{0}, \pi^{2}\right)$. Consequently,

$$
y(t)=C \sin t \sqrt{\lambda_{1}} \geq 0, \quad t \in[0,1] .
$$

It follows from Lemma 2.8 that there exists $\tau_{0}>0$ such that $i(A, P \cap B(\theta, r), P)=0$ for any $0<r \leq \tau_{0}$.

Similarly, we can show that there exists $\tau_{1}>0$ such that $i(A,-P \cap B(\theta, r),-P)=$ 0 for any $0<r \leq \tau_{1}$. Let $r_{0}=\min \left\{\tau_{0}, \tau_{1}\right\}$. Then the conclusion (1) holds and the the proof is complete.

From [6, Theorems 21.6, 21.2], we have the following two lemmas.
Lemma 2.10. Let $A$ be a completely continuous operator, let $x_{0} \in E$ be a fixed point of $A$ and assume that $A$ is defined in a neighborhood of $x_{0}$ and Fréchet differentiable at $x_{0}$. If 1 is not an eigenvalue of the linear operator $A^{\prime}\left(x_{0}\right)$, then $x_{0}$ is an isolated singular point of the completely continuous vector field $I-A$ and for small enough $r>0$

$$
\operatorname{deg}\left(I-A, B\left(x_{0}, r\right), \theta\right)=(-1)^{k}
$$

where $k$ is the sum of the algebraic multiplicities of the real eigenvalues of $A^{\prime}\left(x_{0}\right)$ in $(1,+\infty)$.
Lemma 2.11. Let $A$ be a completely continuous operator which is defined on all $E$. Assume that 1 is not an eigenvalue of the asymptotic derivative. The completely continuous vector field $I-A$ is then nonsingular on spheres $S_{\rho}=\{x \mid\|x\|=\rho\}$ of sufficiently large radius $\rho$ and

$$
\operatorname{deg}(I-A, B(\theta, \rho), \theta)=(-1)^{k}
$$

where $k$ is the sum of the algebraic multiplicities of the real eigenvalues of $A^{\prime}(\infty)$ in $(1,+\infty)$.

## 3. Proof of main Theorem

Proof of Theorem 2.1. From Lemma 2.4, a function $y$ is a solution of the boundaryvalue problem 1.1) if and only if $y$ is a fixed point of the operator $A$. By (H3), we have for any $x \in E,\|x\|=C_{0}$,

$$
\begin{aligned}
&|(A x)(t)| \\
& \leq \frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \int_{0}^{1}(1-s) \max _{s \in[0,1]}|f(x(s))| d s+\int_{0}^{1}(1-s) \max _{s \in[0,1]}|f(x(s))| d s \\
&+\frac{1}{1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \sum_{i=1}^{m-2} \alpha_{i} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right) \max _{s \in[0,1]}|f(x(s))| d s \\
&< \frac{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right.}{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}\left(\frac{1}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}+\frac{1}{2}+\frac{\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{2\left(1-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}\right)}\right) C_{0} \\
& \leq \frac{2 C_{0}}{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}, \quad t \in[0,1] .
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
\|A x\|_{0}<\frac{2 C_{0}}{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} \tag{3.1}
\end{equation*}
$$

Similarly, we can show that for any $x \in E$, with $\|x\|=C_{0}$,

$$
\begin{equation*}
\left\|(A x)^{\prime}\right\|_{0}<\frac{3-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}}{5-\sum_{i=1}^{m-2} \alpha_{i} \eta_{i}} C_{0} \tag{3.2}
\end{equation*}
$$

It follows from (3.1) and (3.2) that $\|A x\|<C_{0}$, for all $\|x\|=C_{0}$. Then, by Lemmas 2.2 and 2.3 we have

$$
\begin{equation*}
i\left(A, P \cap B\left(\theta, C_{0}\right), P\right)=1 \tag{3.3}
\end{equation*}
$$

$$
\begin{equation*}
i\left(A,-P \cap B\left(\theta, C_{0}\right),-P\right)=1 \tag{3.4}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{deg}\left(I-A, B\left(\theta, C_{0}\right), \theta\right)=1 \tag{3.5}
\end{equation*}
$$

By (H2) and Lemma 2.6, the eigenvalues of the operator $A^{\prime}(\theta)=\beta_{0} K$ which are large than 1 are

$$
\frac{\beta_{0}}{\lambda_{1}}, \quad \frac{\beta_{0}}{\lambda_{2}}, \quad \frac{\beta_{0}}{\lambda_{3}}, \ldots, \frac{\beta_{0}}{\lambda_{2 n_{0}}} .
$$

Therefore, by Lemmas 2.6, 2.9, and 2.10, there exists $0<r_{1}<r_{0}$ such that

$$
\begin{equation*}
\operatorname{deg}\left(I-A, B\left(\theta, r_{1}\right), \theta\right)=(-1)^{2 n_{0}}=1 \tag{3.6}
\end{equation*}
$$

Similarly, by Lemmas 2.6, 2.9 and 2.11, we have for some $R_{1} \geq R_{0}$,

$$
\begin{equation*}
\operatorname{deg}\left(I-A, B\left(\theta, R_{1}\right), \theta\right)=1 \tag{3.7}
\end{equation*}
$$

By Lemma 2.9, we have

$$
\begin{gather*}
i\left(A, P \cap B\left(\theta, r_{1}\right), P\right)=0  \tag{3.8}\\
i\left(A,-P \cap B\left(\theta, r_{1}\right),-P\right)=0,  \tag{3.9}\\
i\left(A, P \cap B\left(\theta, R_{1}\right), P\right)=0, \tag{3.10}
\end{gather*}
$$

$$
\begin{equation*}
i\left(A,-P \cap B\left(\theta, R_{1}\right),-P\right)=0 \tag{3.11}
\end{equation*}
$$

Then, by (3.3), (3.8) and (3.10), we have

$$
\begin{gather*}
i\left(A, P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right), P\right)=0-1=-1  \tag{3.12}\\
i\left(A, P \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right), P\right)=1-0=1 \tag{3.13}
\end{gather*}
$$

Therefore, the operator $A$ has at least two fixed points $x_{1} \in P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right)$ and $x_{2} \in P \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right)$, respectively. Obviously, $x_{1}$ and $x_{2}$ are positive solutions of the boundary-value problem (1.1).

Similarly, by (3.4), (3.9) and (3.11), we have

$$
\begin{gather*}
i\left(A,-P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right),-P\right)=-1  \tag{3.14}\\
i\left(A,-P \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right),-P\right)=1 \tag{3.15}
\end{gather*}
$$

Therefore, the operator $A$ has at least two fixed points $x_{3} \in(-P) \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right)$ and $x_{4} \in(-P) \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right)$, respectively. Obviously, $x_{3}$ and $x_{4}$ are negative solutions of the boundary-value problem (1.1).

Let

$$
S=\left\{x \mid x=A x, x \in P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right)\right\} .
$$

It follows from Lemma 2.7 that $S \subset \stackrel{\circ}{P}$. Therefore, for any $x \in S$, there exists $\delta_{x}>0$ such that $B\left(x, \delta_{x}\right) \subset P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right)$. Let $O_{1}=\bigcup_{x \in S} B\left(x, \delta_{x}\right)$. Then, we have $O_{1} \subset P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right)$. By 3.12 and the excision property of the fixed point index, we have

$$
\begin{equation*}
i\left(A, O_{1}, P\right)=-1 \tag{3.16}
\end{equation*}
$$

By the definition of the fixed point index, we have

$$
\begin{equation*}
i\left(A, O_{1}, P\right)=\operatorname{deg}\left(I-A \cdot r, B(\theta, \bar{R}) \cap r^{-1}\left(O_{1}\right), \theta\right) \tag{3.17}
\end{equation*}
$$

where $r: E \mapsto P$ is an arbitrary retraction and $\bar{R}$ is a large enough positive number such that $O_{1} \subset B(\theta, \bar{R})$. Now, we assume that $y^{*} \in B(\theta, \bar{R}) \cap r^{-1}\left(O_{1}\right)$ such that $y^{*}=A \cdot r\left(y^{*}\right)$. Since $r: E \mapsto P$ and $A: P \mapsto P$, then $y^{*} \in P$, and so $y^{*}=r y^{*} \in O_{1}$. Therefore, $y^{*} \in O_{1}$ whenever $y^{*} \in B(\theta, \bar{R}) \cap r^{-1}\left(O_{1}\right)$ is a fixed point of the operator $A \cdot r$. Then, by the excision property of the degree we have

$$
\begin{equation*}
\operatorname{deg}\left(I-A \cdot r, B(\theta, \bar{R}) \cap r^{-1}\left(O_{1}\right), \theta\right)=\operatorname{deg}\left(I-A, O_{1}, \theta\right) \tag{3.18}
\end{equation*}
$$

By (3.16)-(3.18), we have

$$
\begin{equation*}
\operatorname{deg}\left(I-A, O_{1}, \theta\right)=-1 \tag{3.19}
\end{equation*}
$$

Similarly, by (3.13)-3.15), we can show that there exist open sets $O_{2}, O_{3}$ and $O_{4}$ such that

$$
\begin{gather*}
O_{2} \subset P \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right), \\
O_{3} \subset-P \cap\left(B\left(\theta, C_{0}\right) \backslash \overline{B\left(\theta, r_{1}\right)}\right), \\
O_{4} \subset-P \cap\left(B\left(\theta, R_{1}\right) \backslash \overline{B\left(\theta, C_{0}\right)}\right), \\
\operatorname{deg}\left(I-A, O_{2}, \theta\right)=1  \tag{3.20}\\
\operatorname{deg}\left(I-A, O_{3}, \theta\right)=1  \tag{3.21}\\
\operatorname{deg}\left(I-A, O_{4}, \theta\right)=-1 \tag{3.22}
\end{gather*}
$$

It follows from 3.5, 3.6, 3.20 and (3.21) that

$$
\operatorname{deg}\left(I-A, B\left(\theta, C_{0}\right) \backslash\left(\overline{O_{2}} \cup \overline{O_{3}} \cup \overline{B\left(\theta, r_{1}\right)}\right), \theta\right)=1-1-1-1=-2
$$

This implies that $A$ has at least one fixed point $x_{5} \in B\left(\theta, C_{0}\right) \backslash\left(\overline{O_{2}} \cup \overline{O_{3}} \cup \overline{B\left(\theta, r_{1}\right)}\right)$. Similarly, by (3.5), (3.7), (3.19) and (3.22),

$$
\operatorname{deg}\left(I-A, B\left(\theta, R_{1}\right) \backslash\left(\overline{O_{1}} \cup \overline{O_{4}} \cup \overline{B\left(\theta, C_{0}\right)}\right), \theta\right)=1-1+1+1=2 .
$$

This implies that $A$ has at least one fixed point $x_{6} \in B\left(\theta, R_{1}\right) \backslash\left(\overline{O_{1}} \cup \overline{O_{4}} \cup \overline{B\left(\theta, C_{0}\right)}\right)$. Obviously, $x_{5}$ and $x_{6}$ are two distinct sign-changing solutions of the boundary-value problem (1.1). The proof is complete.

By the method used in the proof of Theorem 2.1, it is easy to show the following four corollaries.

Corollary 3.1. Suppose that (H0), (H1) and (H3) hold, and that there exists positive integer $n_{0}$ such that $\lambda_{2 n_{0}}<\beta_{0}<\lambda_{2 n_{0}+1}$. Then the boundary-value problem 1.1) has at least one sign-changing solution. Moreover, the boundary-value problem (1.1) has at least one positive solution and one negative solution.

Corollary 3.2. Suppose that (H0), (H1) and (H3) hold, and that there exists positive integer $n_{1}$ such that $\lambda_{2 n_{1}}<\beta_{1}<\lambda_{2 n_{1}+1}$. Then the conclusion of Corollary 3.1 holds.

Corollary 3.3. Suppose that (HO) and (H1) hold, $\beta_{0}>\lambda_{1}$, $\beta_{1}<\lambda_{1}$ (or $\beta_{0}<\lambda_{1}$, $\beta_{1}>\lambda_{1}$ ). Then the boundary-value problem (1.1) has at least one positive solution and one negative solution.

Corollary 3.4. Suppose that (H0), (H1) and (H3) hold, $\beta_{0}>\lambda_{1}, \beta_{1}>\lambda_{1}$. Then the boundary-value problem (1.1) has at least two positive solutions and two negative solutions.

Remark. In Theorem 2.1, we show not only the existence of multiple signchanging solutions, but also the existence of multiple positive solutions and negative solutions. Obviously, we can employ this method to show the existence of sign-changing solutions for other nonlinear boundary-value problems.
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