Electronic Journal of Differential Equations, Vol. 2006(2006), No. 75, pp. 1-10. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu ftp ejde.math.txstate.edu (login: ftp)

# CONDITIONS FOR THE LOCAL REGULARITY OF WEAK SOLUTIONS OF THE NAVIER-STOKES EQUATIONS NEAR THE BOUNDARY 

PETR KUČERA, ZDENĚK SKALÁK


#### Abstract

In this paper we present conditions for the local regularity of weak solutions of the Navier-Stokes equations near the smooth boundary.


## 1. Introduction

Let $\Omega$ be a bounded domain in $\mathbb{R}^{3}$ with a smooth boundary $\partial \Omega$, let $T>0$ and $Q_{T}=\Omega \times(0, T)$. We consider the Navier-Stokes initial-boundary value problem describing the evolution of the velocity $u=\left(u_{1}, u_{2}, u_{3}\right)$ and the pressure $\phi$ in $Q_{T}$ :

$$
\begin{gather*}
\frac{\partial u}{\partial t}-\nu \Delta u+u \cdot \nabla u+\nabla \phi=0 \quad \text { in } Q_{T}  \tag{1.1}\\
\nabla \cdot u=0 \quad \text { in } Q_{T}  \tag{1.2}\\
u=0 \quad \text { on } \partial \Omega \times(0, T)  \tag{1.3}\\
\left.u\right|_{t=0}=u_{0} \tag{1.4}
\end{gather*}
$$

where $\nu>0$ is the viscosity coefficient. The initial data $u_{0}$ satisfy the compatibility conditions $\left.u_{0}\right|_{\partial \Omega}=0$ and $\nabla \cdot u_{0}=0$ and for our purposes we can suppose without loss of generality that $u_{0}$ is sufficiently smooth. The existence of a weak solution $u \in L^{2}\left(0, T ; W_{0}^{1,2}(\Omega)^{3}\right) \cap L^{\infty}\left(0, T ; L_{\sigma}^{2}(\Omega)\right)$ of 1.1$)-1.4$ is well known (see [4] or [14). The associated pressure $\phi$ is a scalar function such that $u$ and $\phi$ satisfy the equation 1.1) in $Q_{T}$ in the sense of distributions.

Let $q>1$. Let us set

$$
\begin{gathered}
L_{\sigma}^{q}(\Omega)=\text { closure of }\left\{\varphi \in\left(C_{0}^{\infty}(\Omega)\right)^{3} ; \nabla \cdot \varphi=0 \text { in } \Omega\right\} \text { in }\left(L^{q}(\Omega)\right)^{3} \\
G^{q}(\Omega)=\left\{\nabla p ; p \in W^{1, q}(\Omega)\right\}
\end{gathered}
$$

We then have the Helmholtz decomposition

$$
\begin{equation*}
\left(L^{q}(\Omega)\right)^{3}=L_{\sigma}^{q}(\Omega) \oplus G^{q}(\Omega) \quad \text { (direct sum). } \tag{1.5}
\end{equation*}
$$

[^0]Let $P_{\sigma}^{q}$ be the continuous projection from $\left(L^{q}(\Omega)\right)^{3}$ onto $L_{\sigma}^{q}(\Omega)$ associated with Helmholtz decomposition. If $\Delta$ denotes the Laplace operator with zero boundary condition, then the Stokes operator is defined as $A_{q}=-P_{\sigma}^{q} \Delta$ with $D\left(A_{q}\right)=$ $W^{2, q}(\Omega)^{3} \cap W_{0}^{1, q}(\Omega)^{3} \cap L_{\sigma}^{q}(\Omega)$.

In this paper we use both scalar and vector functions and for the sake of simplicity we denote by $S$ any space $S^{3}$ of vector functions with the exception of the notation in Lemma 2.1. We use the standard notation for the Lebesgue spaces $L^{p}(\Omega)$ and their norms $\|\cdot\|_{p, \Omega}$. The Sobolev spaces are denoted by $W^{k, p}(\Omega)$. Sometimes we drop $\Omega$ and write only $L^{p},\|\cdot\|_{p}$ and $W^{k, p}$. Further, if $A=B \times\left(t_{1}, t_{2}\right)$ then $L^{p, q}$ or $L^{p, q}(A)$ denote the space $L^{q}\left(t_{1}, t_{2} ; L^{p}(B)\right)$ with the norm $\|\cdot\|_{p, q, A}$ or simply $\|\cdot\|_{p, q} . L^{p, p}(A)$ is also denoted as $L^{p}(A)$ or $L^{p} . C^{\beta}(\bar{\Omega})$ is the space of Hölder continuous functions on $\Omega$ with the norm $\|f\|_{C^{\beta}(\bar{\Omega})}=\sup _{x \in \Omega}|f(x)|+\sup _{x, y \in \Omega, x \neq y}|f(x)-f(y)| /|x-y|^{\beta}$.
$L_{w}^{p}(\Omega)$ denote the weak Lebesgue space on $\Omega$ with the quasi-norm $\|\cdot\|_{p, w, \Omega}$ defined by $\|\phi\|_{p, w, \Omega}=\sup _{R>0} R \mu\{x \in \Omega ;|\phi(x, t)|>R\}^{1 / p}$, where $\mu$ is the Lebesgue measure. There exists an equivalent norm to $\|\cdot\|_{p, w, \Omega}$, so we may understand $L_{w}^{p}(\Omega)$ as a Banach space. Let us note that $L^{p}(\Omega) \subset L_{w}^{p}(\Omega)$ and $\|\phi\|_{p, w, \Omega} \leq\|\phi\|_{p}$ for every $\phi \in L^{p}(\Omega)$. Sometimes we write $L_{w}^{p}$ and $\|\phi\|_{p, w}$ instead of $L_{w}^{p}(\Omega)$ and $\|\phi\|_{p, w, \Omega}$, respectively.

For $\left(x_{0}, t_{0}\right) \in \bar{\Omega} \times(0, T)$ and $r>0$ we will denote $B_{r}=B_{r}\left(x_{0}\right)$ the open ball centered at $x_{0}$ with radius $r, D_{r}=D_{r}\left(x_{0}\right)=B_{r}\left(x_{0}\right) \cap \Omega, Q_{r}=Q_{r}\left(x_{0}, t_{0}\right)=$ $D_{r}\left(x_{0}\right) \times\left(t_{0}-r^{2}, t_{0}+r^{2}\right)$. A point $\left(x_{0}, t_{0}\right) \in \bar{\Omega} \times(0, T)$ is called a regular point of a weak solution $u$ if $u \in L^{\infty}\left(Q_{r}\right)$ for some $r>0$. Otherwise, $\left(x_{0}, t_{0}\right)$ is called a singular point of $u$.

Let us now present some recent results concerning the regularity of weak solutions near the boundary. S.Takahashi showed in [12] and [13] that if $u \in L^{p, q}\left(Q_{r}\right)$, where $\left(x_{0}, t_{0}\right) \in \partial \Omega \times(0, T), r>0, p, q \in(1, \infty)$ and $3 / p+2 / q \leq 1$, then $u \in L^{\infty}\left(Q_{\tilde{r}}\right)$ for any $\tilde{r} \in(0, r)$ provided that $B_{r} \cap \partial \Omega$ is a part of a plane.

Takahashi's result was improved in [11], where the following theorem was proved.
Theorem 1.1. Let $u$ be an arbitrary weak solution of (1.1) - 1.4), $\left(x_{0}, t_{0}\right) \in$ $\partial \Omega \times(0, T), r>0$. We suppose that $u \in L^{p, q}\left(Q_{r}\right)$, where $2 / q+3 / p=1$ and $p, q \in(1, \infty)$. Then

$$
\begin{equation*}
u \in L^{\infty}\left(t_{0}-\tilde{r}^{2}, t_{0}+\tilde{r}^{2} ; C^{\beta}\left(\bar{D}_{\tilde{r}}\right)\right) \tag{1.6}
\end{equation*}
$$

for every $\beta \in(0,1)$ and $\tilde{r} \in(0, r)$.
Neustupa [9] proved a similar result. He supposed that $u \in L^{q}\left(t_{1}, t_{2} ; L^{p}\left(U_{r}^{*}\right)\right)$ for some $r>0,0<t_{1}<t_{2}<T, p, q \in(1, \infty)$ with $3 / p+2 / q=1$, where $U_{r}^{*}=\{x \in \Omega ; \operatorname{dist}(x, \partial \Omega)<r\}$. He proved under this assumption that if $u$ is a weak solution of $(1.1)-(\sqrt{1.4})$ satisfying the strong energy inequality then $u \in$ $L^{\infty}\left(t_{1}+\zeta, t_{2}-\zeta ; W^{2+\delta, 2}\left(U_{\rho}^{*}\right)\right)$ and $\partial u / \partial t, \nabla \phi \in L^{\infty}\left(t_{1}+\zeta, t_{2}-\zeta ; W^{\delta, 2}\left(U_{\rho}^{*}\right)\right)$ for each $\delta \in[0,1 / 2), \rho \in(0, r)$ and such $\zeta>0$ that $t_{1}+\zeta<t_{2}-\zeta$.

The local boundary regularity of $u$ was also studied in [2], 10] and [6]. It was proved in [2] that a suitable weak solution $u$ is bounded locally near the boundary if $u \in L^{p, q}, 3 / p+2 / q=1, p, q \in(1, \infty)$ and the pressure $\phi$ is bounded at the boundary. Moreover, better regularity of $\phi$ gives better local regularity of $u$. Seregin presented in 10 a condition for local Hölder continuity for suitable weak solutions near the plane boundary which has the form of the famous Caffarelli-Kohn-Nirenberg condition for boundedness of suitable weak solutions in a neighborhood of an interior point of $Q_{T}$. Also Kang [6] studied boundary regularity of weak solutions in the
half-space. He proved that a weak solution $u$ which is locally in the class $L^{p, q}$ with $3 / p+2 / q=1$ and $p, q \in(1, \infty)$ near the boundary is Hölder continuous up to the boundary. The main tool in the proof of this result is a pointwise estimate for the fundamental solution of the Stokes system.

In this paper we present some conditions ensuring the local regularity of weak solutions near the boundary. The following theorem is our main result.

Theorem 1.2. Let $u=\left(u_{1}, u_{2}, u_{3}\right)$ be an arbitrary weak solution of (1.1)-(1.4). There exists $\varepsilon>0$ such that if $\left(x_{0}, t_{0}\right) \in \partial \Omega \times(0, T), r>0$ and at least one of the following conditions is fulfilled:
(A1) $\|u\|_{L^{\infty}\left(t_{0}-r^{2}, t_{0}+r^{2} ; L_{\omega}^{3}\left(D_{r}\right)\right)}<\varepsilon$,
(A2) $\nabla u \in L^{3,2}\left(Q_{r}\right)$,
(A3) $\nabla u_{1}, \nabla u_{2} \in L^{p, q}\left(Q_{r}\right), p \in(3 / 2, \infty], q \in(2, \infty], 3 / p+2 / q \leq 2$,
(A4) $\nabla u_{1}, \nabla u_{2} \in L^{p, q}\left(Q_{r}\right), p \in(3, \infty], q=2$.
Then, for every $\beta \in(0,1)$ and $\tilde{r} \in(0, r)$,

$$
\begin{equation*}
u \in L^{\infty}\left(t_{0}-\tilde{r}^{2}, t_{0}+\tilde{r}^{2} ; C^{\beta}\left(\bar{D}_{\tilde{r}}\right)\right) \tag{1.7}
\end{equation*}
$$

Remark 1.3. We can compare conditions (A3) and (A4) with Theorem 1.2 from [1], where the regularity of $u$ was proved under the assumption that $\nabla u_{1}, \nabla u_{2} \in$ $L^{p, q}, p \in[3, \infty], q \in[2, \infty]$ and $3 / p+2 / q=1$. If this assumption holds than either the condition (A3) or the condition (A4) is satisfied. Thus, in this sense, Theorem 1.2 is a generalization of Theorem 1.2 from [1].

The proof of Theorem 1.2 will be based on Takahashi 12, and Theorem 1.1 will be a corollay of Theorem 1.2 Firstly, we present some auxiliary results.

## 2. Auxiliary results

We will use the following lemma which was proved in 12 and in 3, Theorem 3.2, Chap.III.3].

Lemma 2.1. Let $D$ be a bounded Lipschitz domain in $\mathbb{R}^{3}, \Gamma$ be an open subset of $\partial D, r \in(1, \infty), j \in N \cup\{0\}$. There exists a bounded linear operator $K=K_{j, r, D, \Gamma}$ : $W_{0}^{j, r}(D) \rightarrow W_{0}^{j+1, r}(D)^{3}$ such that
(i) $\nabla \cdot K g=g$ for all $g \in W_{0}^{j, r}(D)$ such that $\int_{D} g d x=0$,
(ii) $\left\|\nabla^{j+1} K g\right\|_{r} \leq c\left\|\nabla^{j} g\right\|_{r}$ for all $g \in W_{0}^{j, r}(D), c=c(j, r, D)$
(iii) $\operatorname{supp} K g \subset D \cup \Gamma$ if $\operatorname{supp} g \subset D \cup \Gamma$.

In Lemma 2.1. $W_{0}^{j, r}(D)$ is the completion of $C_{0}^{\infty}(D)$ with respect to the standard norm of the space $W^{j, r}(D)$. It is possible to show that $K_{j, r, D, \Gamma}(g)=K_{l, s, G, \Gamma}(g)$ if $g \in W_{0}^{j, r}(D) \cap W_{0}^{l, s}(D)$, where $r, s \in(1, \infty)$ and $j, l \in N \cup\{0\}$ and in the rest of the paper the operator $K_{j, r, D, \Gamma}$ is denoted by $K$.

For $l, l^{\prime} \in(1, \infty)$ we define the Banach space

$$
X^{l, l^{\prime}}=\left\{v \in L^{l^{\prime}}\left(0, T, D\left(A_{l}\right)\right) ; \frac{\partial v}{\partial t} \in L^{l^{\prime}}\left(0, T, L_{\sigma}^{l}(\Omega)\right), v(0)=0\right\}
$$

with the norm

$$
\|v\|_{X^{l, l^{\prime}}}=\left\|A_{l} v\right\|_{l, l^{\prime}}+\left\|\frac{\partial v}{\partial t}\right\|_{l, l^{\prime}}
$$

We consider the Stokes problem

$$
\begin{gather*}
\frac{\partial u}{\partial t}-\nu \Delta u+\nabla \phi=f \quad \text { in } Q_{T}  \tag{2.1}\\
\nabla \cdot u=0 \quad \text { in } Q_{T}  \tag{2.2}\\
u=0 \quad \text { on } \partial \Omega \times(0, T)  \tag{2.3}\\
\left.u\right|_{t=0}=0 \tag{2.4}
\end{gather*}
$$

It was proved in [5, Theorem 2.8] that if $f \in L^{\beta, \beta^{\prime}}$, where $\beta, \beta^{\prime} \in(1, \infty)$, then there exists a unique weak solution $(u, \nabla \phi)$ of $2.1-2.4$ such that

$$
\begin{equation*}
\left\|\frac{\partial u}{\partial t}\right\|_{\beta, \beta^{\prime}}+\left\|A_{\beta} u\right\|_{\beta, \beta^{\prime}}+\|\nabla \phi\|_{\beta, \beta^{\prime}} \leq c\|f\|_{\beta, \beta^{\prime}}, c=c\left(\beta, \beta^{\prime}\right) \tag{2.5}
\end{equation*}
$$

The following lemma was proved in [12] and [11]. It further improves the regularity of the velocity $u$.
Lemma 2.2. Let $\beta, \beta^{\prime} \in(1, \infty), \gamma \in[\beta, \infty), \gamma^{\prime} \in\left[\beta^{\prime}, \infty\right)$ and

$$
\begin{equation*}
\frac{2}{\beta^{\prime}}+\frac{3}{\beta}=\frac{2}{\gamma^{\prime}}+\frac{3}{\gamma}+1 \tag{2.6}
\end{equation*}
$$

Let $f \in L^{\beta, \beta^{\prime}}$. If $(u, \nabla \phi)$ is a weak solution of 2.1-2.4 then $\nabla u \in L^{\gamma, \gamma^{\prime}}$ and

$$
\begin{equation*}
\|\nabla u\|_{\gamma, \gamma^{\prime}} \leq c\|f\|_{\beta, \beta^{\prime}}, \quad c=c\left(\beta, \beta^{\prime}, \gamma, \gamma^{\prime}\right) . \tag{2.7}
\end{equation*}
$$

Lemma 2.3. Let $u \in L^{\infty}\left(0, T, L_{\omega}^{3}(\Omega)\right), v \in L^{s}\left(0, T ; W^{2, r}(\Omega) \cap W_{0}^{1, r}(\Omega)\right), r \in(1,3)$, $s \in(1,2)$. Then

$$
\begin{equation*}
\|u \cdot \nabla v\|_{r, s} \leq C\|u\|_{L^{\infty}\left(0, T, L_{w}^{3}(\Omega)\right)}\|\cdot\| v \|_{L^{s}\left(0, T ; W^{2, r}(\Omega)\right)} \tag{2.8}
\end{equation*}
$$

Proof. We use the procedure used in [7, Lemma 2.7]. Let $1<r_{0}<r<r_{1}<3$ and $\frac{1}{r}=\frac{1-\theta}{r_{0}}+\frac{\theta}{r_{1}}$ for some $\theta \in(0,1)$. Let $\frac{1}{q_{j}}=\frac{1}{r_{j}}-\frac{1}{3}, j=0,1$. We can write for every $w \in D\left(\Delta_{r_{j}}\right)=W^{2, r_{j}}(\Omega) \cap W_{0}^{1, r_{j}}(\Omega):$

$$
\begin{aligned}
\|u \cdot \nabla w\|_{r_{j}, \omega} & \leq C\|u\|_{3, \omega}\|\nabla w\|_{q_{j}, \omega} \leq C\|u\|_{3, \omega}\|\nabla w\|_{q_{j}} \\
& \leq C\|u\|_{3, \omega}\|w\|_{W^{2, r_{j}}} \leq C\|u\|_{3, \omega}\left\|\Delta_{r_{j}} w\right\|_{r_{j}} .
\end{aligned}
$$

If $\phi \in L^{r_{j}}$ and we put $w=\Delta_{r_{j}}^{-1} \phi$, we get

$$
\left\|u \cdot \nabla\left(\Delta_{r_{j}}^{-1} \phi\right)\right\|_{r_{j}, \omega} \leq C\|u\|_{3, \omega}\|\phi\|_{r_{j}}
$$

Therefore, the mapping $\phi \rightarrow u \cdot \nabla\left(\Delta_{r_{j}}^{-1} \phi\right)$ is a linear bounded operator from $L^{r_{j}}$ into $L_{\omega}^{r_{j}}$ with the norm less than $C\|u\|_{3, \omega}$. By the use of the Marcinkiewicz interpolation theorem (see [8], p.106) we get that it is also a linear bounded operator from $L^{r}$ into $L^{r}$ with the norm less than $C\|u\|_{3, \omega}$, that is

$$
\left\|u \cdot \nabla\left(\Delta_{r}^{-1} \phi\right)\right\|_{r} \leq C\|u\|_{3, \omega}\|\phi\|_{r}
$$

for every $\phi \in L^{r}$. If $w \in D\left(\Delta_{r}\right)$, then $\Delta_{r} w \in L^{r}$ and

$$
\|u \cdot \nabla w\|_{r}=\left\|u \cdot \nabla\left(\Delta_{r}^{-1}\left(\Delta_{r} w\right)\right)\right\|_{r} \leq C\|u\|_{3, \omega}\left\|\Delta_{r} w\right\|_{r} \leq C\|u\|_{3, \omega}\|w\|_{W^{2, r}(\Omega)}
$$

Inequality 2.8 now follows easily from the Hölder inequality.
Lemma 2.4. Let $\nabla u \in L^{p, q}\left(Q_{T}\right), p \in(3 / 2,3], q \in[2, \infty)$ and $3 / p+2 / q=2$. Let $v \in X^{r, s}, r \in(1, p), s \in(1, q)$. Then

$$
\begin{equation*}
\|v \cdot \nabla u\|_{r, s} \leq C\|\nabla u\|_{p, q} \cdot\|v\|_{X^{r, s}} . \tag{2.9}
\end{equation*}
$$

Proof. Since $v \in X^{r, s}$, it follows from Lemma 2.2 that $\nabla v \in L^{\frac{3 q r}{2 r+3 q-q r}, \frac{q s}{q-s}}$ and

$$
\|\nabla v\|_{\frac{3 q r}{2 r+3 q-q r}, \frac{q s}{q-s}} \leq c\|v\|_{X^{r, s}}
$$

The Sobolev inequality gives immediately that $\|v\|_{\frac{p r}{p-r}, \frac{q s}{q-s}} \leq C\|v\|_{X^{r, s}}$. The Hölder inequality yields that $\|v \cdot \nabla u\|_{r, s} \leq\|\nabla u\|_{p, q} \cdot\|v\|_{\frac{p r}{p-r}, \frac{q s}{q-s}}$ and 2.9 is the consequence of the last two inequalities.
Lemma 2.5. Let $u \in L^{p, q}\left(Q_{T}\right), p \in(3, \infty], q \in[2, \infty), 3 / p+2 / q=1$. Let $v \in X^{r, s}, r \in(1, p), s \in(1, q)$. Then

$$
\begin{equation*}
\|u \cdot \nabla v\|_{r, s} \leq c\|u\|_{p, q} \cdot\|v\|_{X^{r, s}} \tag{2.10}
\end{equation*}
$$

Proof. Let $p<\infty$. Using Lemma 2.2,

$$
\|\nabla v\|_{\frac{p r}{p-r}, \frac{q s}{q-s}} \leq c\|v\|_{X^{r, s}}
$$

Since $\|u \cdot \nabla v\|_{r, s} \leq\|u\|_{p, q} \cdot\|\nabla v\|_{\frac{p r}{p-r}, \frac{q s}{q-s}, 2.10}$ follows immediately. If $p=\infty$, then the proof proceeds analogically.
Lemma 2.6. Let $\nabla u \in L^{p, q}\left(Q_{T}\right), p \in(3 / 2,3], q \in[2, \infty)$ and $3 / p+2 / q=2$. Let further $r \in(1, p)$, $s \in(2 q /(q+2), q), 3 / r+2 / s=3$ and $w \in L^{\rho}\left(0, T ; W^{2, h}\right)$ for every $h \in(1,3)$ and $\rho \in(1, \infty)$ such that $2 / \rho+3 / h=3$. Then

$$
\begin{equation*}
w \cdot \nabla u \in L^{r, s}\left(Q_{T}\right) \tag{2.11}
\end{equation*}
$$

Proof. If we choose $\rho=q s /(q-s)$ and $h=3 q s /(3 q s-2 q+2 s)$, then $\rho \in(2, \infty)$, $h \in(1,3 / 2), 3 / h+2 / \rho=3$ and $w \in L^{\rho}\left(0, T ; W^{2, h}\right)$. Consequently, by the Sobolev inequality

$$
\|w\|_{\frac{p r}{p-r}, \frac{q s}{q-s}} \leq C\|w\|_{L^{\rho}\left(0, T ; W^{2, h}\right)}
$$

and 2.11 follows from the inequality $\|w \cdot \nabla u\|_{r, s} \leq\|\nabla u\|_{p, q}\|w\|_{\frac{p r}{p-r}, \frac{q s}{q-s}}$.
Lemma 2.7. Let $u \in L^{q}\left(0, T ; W_{0}^{1, p}(\Omega)\right), p \in(3 / 2,3), q \in(2, \infty)$ and $3 / p+2 / q=2$. Let further $r \in(1,3), s \in(1, q), 3 / r+2 / s=3$ and $w \in L^{\rho}\left(0, T ; W^{2, h}\right)$ for every $h \in(1,3)$ and $\rho \in(1, \infty)$, such that $2 / \rho+3 / h=3$. Then

$$
\begin{equation*}
u \cdot \nabla w \in L^{r, s}\left(Q_{T}\right) \tag{2.12}
\end{equation*}
$$

Proof. Let us put $p^{\prime}=3 p /(3-p)$. Then $u \in L^{p^{\prime}, q}\left(Q_{T}\right)$. Further,

$$
\nabla w \in L^{\rho}\left(0, T ; L^{h^{\prime}}\right)
$$

for every $h^{\prime} \in(3 / 2, \infty), \rho \in(1, \infty)$ such that $2 / \rho+3 / h^{\prime}=2$. If we choose $h^{\prime}=p^{\prime} r /\left(p^{\prime}-r\right)$ and $\rho=q s /(q-s), 2.12$ then follows immediately from the inequality $\|u \cdot \nabla w\|_{r, s} \leq\|u\|_{p^{\prime}, q}\|\nabla w\|_{h^{\prime}, \rho}$.
Remark 2.8. Lemma 2.7 holds also if $p>3$ and $q=2$. In this case we have $p^{\prime}=\infty$ and $h^{\prime}=r$.

We now denote

$$
\begin{gathered}
B_{1}(u, v)=u \cdot \nabla v=\left(u_{j} \frac{\partial v_{1}}{\partial x_{j}}, u_{j} \frac{\partial v_{2}}{\partial x_{j}}, u_{j} \frac{\partial v_{3}}{\partial x_{j}}\right) \\
B_{2}(u, v)=v \cdot \nabla u=\left(v_{j} \frac{\partial u_{1}}{\partial x_{j}}, v_{j} \frac{\partial u_{2}}{\partial x_{j}}, v_{j} \frac{\partial u_{3}}{\partial x_{j}}\right), \\
B_{3}(u, v)=B_{4}(u, v)=\left(v_{j} \frac{\partial u_{1}}{\partial x_{j}}, v_{j} \frac{\partial u_{2}}{\partial x_{j}}, u_{1} \frac{\partial v_{3}}{\partial x_{1}}+u_{2} \frac{\partial v_{3}}{\partial x_{2}}-v_{3}\left(\frac{\partial u_{1}}{\partial x_{1}}+\frac{\partial u_{2}}{\partial x_{2}}\right)\right) .
\end{gathered}
$$

Lemma 2.9. Let $i \in\{1,2,3,4\}, l^{\prime} \in(1,2), l \in(1,3)$. Let us consider the following conditions:
(1) $u \in L^{\infty}\left(0, T ; L_{\omega}^{3}(\Omega)\right)$,
(2) $\nabla u \in L^{3,2}\left(Q_{T}\right)$,
(3) $u_{1}, u_{2} \in L^{q}\left(0, T ; W_{0}^{1, p}(\Omega)\right), p \in(3 / 2, \infty], q \in(2, \infty], 3 / p+2 / q \leq 2$,
(4) $u_{1}, u_{2} \in L^{q}\left(0, T ; W_{0}^{1, p}(\Omega)\right), p \in(3, \infty], q=2$.

If condition (1) is satisfied and if moreover $l \in(1, p)$ for $i=3$, then the operator $v \mapsto B_{i}(u, v)$ is a linear bounded operator from $X^{l, l^{\prime}}$ into $L^{l, l^{\prime}}$ with the norm less than $C\|u\|_{L^{\infty}\left(0, T, L_{\omega}^{3}(\Omega)\right)}$ for $i=1, C\|\nabla u\|_{3,2}$ for $i=2$ and $C\left(\left\|\nabla u_{1}\right\|_{p, q}+\left\|\nabla u_{2}\right\|_{p, q}\right)$ for $i=3,4$.

Proof. If $i=1$ then the proof follows immediately from Lemma 2.3. If $i=2$ then the proof follows immediately from Lemma 2.4. If $i=3$ and $i=4$ the proof is the consequence of Lemma 2.4 and Lemma 2.5 .

For $i \in\{1,2,3,4\}$ let us consider the problem

$$
\begin{gather*}
\frac{\partial v}{\partial t}-\nu \Delta v+B_{i}(u, v)+\nabla P=g \quad \text { in } Q_{T}  \tag{2.13}\\
\nabla \cdot v=0 \quad \text { in } Q_{T}  \tag{2.14}\\
v=0 \quad \text { on } \partial \Omega \times(0, T)  \tag{2.15}\\
\left.v\right|_{t=0}=0 \tag{2.16}
\end{gather*}
$$

Lemma 2.10. Let $i \in\{1,2,3,4\}$. Let $g \in L^{l, l^{\prime}}, 2 / l^{\prime}+3 / l=3, l^{\prime} \in(1,2), l \in$ $(3 / 2,3)$. Let the condition i) from Lemma 2.9 be fulfilled and $C\|u\|_{L^{\infty}\left(0, T ; L_{\omega}^{3}(\Omega)\right)}<\varepsilon$ for $i=1, C\|\nabla u\|_{3,2}<\varepsilon$ for $i=2, C\left(\left\|\nabla u_{1}\right\|_{p, q}+\left\|\nabla u_{2}\right\|_{p, q}\right)<\varepsilon$ and $l \in(3 / 2, p)$ for $i=3$ and $C\left(\left\|\nabla u_{1}\right\|_{p, q}+\left\|\nabla u_{2}\right\|_{p, q}\right)<\varepsilon$ for $i=4$, where $\varepsilon$ is a sufficiently small positive number. Then there exists a unique $v \in X^{l, l^{\prime}}$ and $\nabla P \in L^{l, l^{\prime}}$, which solve the problem 2.13- 2.16 .

Proof. The operator $v \rightarrow \frac{\partial v}{\partial t}+A_{l} v$ is one to one linear bounded operator from $X^{l, l^{\prime}}$ onto $L^{l^{\prime}}\left(0, T ; L_{\sigma}^{l}\right)$. According to Lemma 2.9, the norm of the operator $v \rightarrow$ $P_{\sigma}^{l} B_{i}(u, v)$ is sufficiently small. Accordingly, the operator $v \rightarrow \frac{\partial v}{\partial t}+A_{l} v+P_{\sigma}^{l} B_{i}(u, v)$ is one to one linear bounded operator from $X^{l, l^{\prime}}$ onto $L^{l^{\prime}}\left(0, T ; L_{\sigma}^{l}\right)$. Therefore, there exists a unique $v \in X^{l, l^{\prime}}$ such that

$$
\frac{\partial v}{\partial t}+A_{l} v+P_{\sigma}^{l} B_{i}(u, v)=P_{\sigma}^{l} g
$$

that is

$$
P_{\sigma}^{l}\left(\frac{\partial v}{\partial t}-\nu \Delta v+B_{i}(u, v)-g\right)=0
$$

holds for almost every $t \in(0, T)$. The existence of $P$ such that (2.13) follows from Helmholtz decomposition of the space $L^{l}$.

## 3. Proof of Theorem 1.2

We suppose throughout this section that the assumptions of Theorem 1.2 are satisfied. Let $i \in\{1,2,3,4\}$ be fixed and the condition (Ai) from Theorem 1.2 be fulfilled. $\phi$ denotes the associated pressure to $u$. Let $\tilde{r} \in(0, r)$. Let us localize the problem (1.1)-(1.4) in a standard way: Let $\psi \in C^{\infty}\left(\bar{Q}_{T}\right)$ be a cut-off function such that $\psi(x, t)=0$ if $(x, t) \in Q_{T} \backslash \bar{Q}_{2 r / 3+\tilde{r} / 3}, \psi(x, t)=1$ if $(x, t) \in Q_{r / 3+2 \tilde{r} / 3}$ and
$\psi(x, t) \in[0,1]$ for every $(x, t) \in Q_{T}$. We set $w=K(\nabla \cdot(\psi u)), v=\psi u-w$, where $K=K_{D_{r}}$. Then $v$ satisfies the following system of equations:

$$
\begin{gather*}
\frac{\partial v}{\partial t}-\nu \Delta v+B_{i}(u, v)+\nabla(\psi \phi)=h^{i} \quad \text { in } Q_{T}  \tag{3.1}\\
\nabla \cdot v=0 \quad \text { in } Q_{T}  \tag{3.2}\\
v=0 \quad \text { on } \partial \Omega \times(0, T)  \tag{3.3}\\
\left.v\right|_{t=0}=0 \tag{3.4}
\end{gather*}
$$

where

$$
\begin{gathered}
h^{1}=-\nu \Delta \psi u-2 \nu \nabla \psi \cdot \nabla u+u \cdot \nabla \psi u+\phi \nabla \psi-\frac{\partial w}{\partial t}+\nu \Delta w-u \cdot \nabla w+\frac{\partial \psi}{\partial t} u \\
h^{2}=-\nu \Delta \psi u-2 \nu \nabla \psi \cdot \nabla u+\phi \nabla \psi-\frac{\partial w}{\partial t}+\nu \Delta w-w \cdot \nabla u+\frac{\partial \psi}{\partial t} u \\
h^{3}=h^{4}=\left(h_{1}^{3}, h_{2}^{3}, h_{3}^{3}\right) \\
h_{i}^{3}=-\nu \Delta \psi u_{i}-2 \nu \nabla \psi \cdot \nabla u_{i}+\phi \frac{\partial \psi}{\partial x_{i}}-\frac{\partial w_{i}}{\partial t}+\nu \Delta w_{i}-w \cdot \nabla u_{i}+\frac{\partial \psi}{\partial t} u_{i}, \quad i=1,2, \\
h_{3}^{3}=-\nu \Delta \psi u_{3}-2 \nu \nabla \psi \cdot \nabla u_{3}+\phi \frac{\partial \psi}{\partial x_{3}}-\frac{\partial w_{3}}{\partial t}+\nu \Delta w_{3}+\frac{\partial \psi}{\partial t} u_{3} \\
+u_{1} \frac{\partial \psi}{\partial x_{1}} u_{3}+u_{2} \frac{\partial \psi}{\partial x_{2}} u_{3}-u_{1} \frac{\partial w_{3}}{\partial x_{1}}-u_{2} \frac{\partial w_{3}}{\partial x_{2}}+w_{3} \frac{\partial u_{1}}{\partial x_{1}}+w_{3} \frac{\partial u_{2}}{\partial x_{2}} .
\end{gathered}
$$

Remark 3.1. We can proceed in such a way that both supp $w$ and $\operatorname{supp} v$ lie in $\bar{Q}_{3 r / 4+\tilde{r} / 4}$. Therefore, it is possible to replace the function $u$ in the term $B_{i}(u, v)$ and also in the right hand side $h^{i}$ of 3.1 with a function $\eta u$, where $\eta \in C^{\infty}\left(\bar{Q}_{T}\right)$ is such a cut-off function that $\eta(x, t)=0$ if $(x, t) \in Q_{T} \backslash \bar{Q}_{r}, \eta(x, t)=1$ if $(x, t) \in Q_{3 r / 4+\tilde{r} / 4}$ and $\eta(x, t) \in[0,1]$ for every $(x, t) \in Q_{T}$. For the sake of simplicity we still write $u$ instead of $\eta u$.

We will show at first that

$$
\begin{equation*}
h^{i} \in L^{l, l^{\prime}}, \text { for some } l^{\prime} \in(1,2), l \in(3 / 2,3) \text { such that } \frac{2}{l^{\prime}}+\frac{3}{l}=3 \tag{3.5}
\end{equation*}
$$

We will use the following global estimates for $u$ and $\phi$ derived in [5], Theorem 3.1:

$$
\begin{gather*}
\left\|\frac{\partial u}{\partial t}\right\|_{q, s}+\left\|\nabla^{2} u\right\|_{q, s}+\|\nabla \phi\|_{q, s}<\infty, \quad s \in(1,2), q \in(1,3 / 2), \frac{2}{s}+\frac{3}{q}=4  \tag{3.6}\\
\|\nabla u\|_{h, \rho}<\infty, \quad h \in(1,3), \rho \in(1, \infty), \frac{2}{\rho}+\frac{3}{h}=3  \tag{3.7}\\
\|u\|_{h^{*}, \rho}<\infty, \quad h^{*} \in(3 / 2, \infty), \rho \in(1, \infty), \frac{2}{\rho}+\frac{3}{h^{*}}=2 \tag{3.8}
\end{gather*}
$$

and

$$
\begin{align*}
\|\phi\|_{r, s} & <\infty, \quad r \in(3 / 2,3), \quad s \in(1,2), \quad \frac{2}{s}+\frac{3}{r}=3 \\
& \text { if } \int_{\Omega} \phi(x, t) d x=0 \text { for every } t \in(0, T) \tag{3.9}
\end{align*}
$$

We have immediately from (3.9) that $\phi \nabla \psi \in L^{l, l^{\prime}}$. It follows from Lemma 2.1 that

$$
\left\|\frac{\partial w}{\partial t}\right\|_{l, l^{\prime}}=\left\|\frac{\partial}{\partial t}(K(\nabla \psi \cdot u))\right\|_{l, l^{\prime}}=\left\|K\left(\frac{\partial}{\partial t}(\nabla \psi \cdot u)\right)\right\|_{l, l^{\prime}} \leq c\left\|\frac{\partial}{\partial t}(\nabla \psi \cdot u)\right\|_{q, l^{\prime}}
$$

where $1 / q=1 / l+1 / 3$. Since $2 / l^{\prime}+3 / q=4$, we have $\partial w / \partial t \in L^{l, l^{\prime}}$ by (3.6. Similarly, $\nu \Delta w \in L^{l, l^{\prime}}$, as follows from Lemma 2.1 and 3.7).

Let us show that also the terms of the type $u \cdot \nabla w$ and $w \cdot \nabla u$ are from $L^{l, l^{\prime}}$ for some $l^{\prime} \in(1,2), l \in(3 / 2,3)$ such that $2 / l^{\prime}+3 / l=3$. By (3.7), $u \in L^{\rho}\left(0, T ; W_{0}^{1, h}(\Omega)\right)$, for every $h, \rho$ such that $2 / \rho+3 / h=3, h \in(1,3), \rho \in(1, \infty)$. Consequently, Lemma 2.1 gives that $w \in L^{\rho}\left(0, T ; W_{0}^{2, h}(\Omega)\right)$. Let us note that in the following paragraphs we use Remark 3.1.

If $i=1$, it follows from Lemma 2.3 that

$$
\|u \cdot \nabla w\|_{l, l^{\prime}, \Omega} \leq C\|u\|_{L^{\infty}\left(t_{0}-r^{2}, t_{0}+r^{2}, L_{\omega}^{3}\left(D_{r}\right)\right)}\|\cdot\| w \|_{L^{l^{\prime}\left(0, T, W^{2, l}(\Omega)\right)}}<\infty
$$

and $u \cdot \nabla w \in L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from $\sqrt{3.5}$ ).
If $i=2$, it follows from Lemma 2.6 that $w \cdot \nabla u \in L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from 3.5).
Let $i=3$. We apply Lemma 2.6 and get: If moreover $p \geq 3$ then the terms $w \cdot \nabla u$ are in $L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from (3.5). If $p \in(3 / 2,3)$ and $q \in(2, \infty)$ then the terms $w \cdot \nabla u$ are in $L^{l, l^{\prime}}$ for $l \in(1, p)$ and $l^{\prime} \in(2 q /(q+2), q)$. If $p \in(3 / 2,3)$ and $q=\infty$ then the terms $w \cdot \nabla u$ are in $L^{l, l^{\prime}}$ for $l \in(1, p)$ and $l^{\prime} \in(2 p /(3 p-3), 2)$. Similarly, using Lemma 2.7 we get that the terms $u \cdot \nabla w$ are in $L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from (3.5).

Finally, let $i=4$. Then the terms $w \cdot \nabla u$ are in $L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from (3.5), as follows easily from Lemma 2.6. Similarly, the terms $u \cdot \nabla w$ are in $L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from (3.5) due to Lemma 2.7 and Remark 2.8 .

The remaining terms in $h^{i}, i=1,2,3,4$ belong obviously to the space $L^{l, l^{\prime}}$ for every $l, l^{\prime}$ from $\sqrt{3.5}$ and $\sqrt{3.5}$ is proved.

Proof of Theorem 1.2. Let us fix now $l, l^{\prime}$ from (3.5) such that $h^{i} \in L^{l, l^{\prime}}$. Let $\tilde{v} \in X^{l, l^{\prime}}$ and $P, \nabla P \in L^{l, l^{\prime}}$, solve the equations (3.1) - 3.4. The existence of this solution follows from Lemma 2.9. Lemma 2.10 and Remark 3.1, since the norm of the operator $B_{i}(u, \cdot)$ is or can be made sufficiently small due to the condition $\left(a_{i}\right)$. Then $V=\tilde{v}-v$ and $p=P-\psi \phi$ solve the equations 2.13-2.16 with the right hand side 0 and $V \in X^{q, s}$ and $\nabla p \in L^{q, s}$, where $q, s$ fulfil conditions from (3.6). Transferring now the term $B_{i}(u, V)$ to the right hand side and using 2.5 and Lemma 2.9, we obtain that

$$
\begin{gathered}
\|V\|_{X^{q, s}} \leq C\|u\|_{L^{\infty}\left(t_{0}-r^{2}, t_{0}+r^{2} ; L_{\omega}^{3}\left(D_{r}\right)\right)}\|V\|_{X^{q, s}} \quad \text { if } i=1, \\
\|V\|_{X^{q, s}} \leq C\|\nabla u\|_{3,2, Q_{r}}\|V\|_{X^{q, s}} \quad \text { if } i=2, \\
\|V\|_{X^{q, s}} \leq C\left(\left\|\nabla u_{1}\right\|_{p, q, Q_{r}}+\left\|\nabla u_{2}\right\|_{p, q, Q_{r}}\right)\|V\|_{X^{q, s}} \quad \text { if } i=3, \\
\|V\|_{X^{q, s}} \leq C\left(\left\|\nabla u_{1}\right\|_{p, 2, Q_{r}}+\left\|\nabla u_{2}\right\|_{p, 2, Q_{r}}\right)\|V\|_{X^{q, s}} \quad \text { if } i=4 .
\end{gathered}
$$

While $C\|u\|_{L^{\infty}\left(t_{0}-r^{2}, t_{0}+r^{2} ; L_{\omega}^{3}\left(D_{r}\right)\right)}<1$ due to the assumption (A1) in Theorem 1.2 (supposing that $\varepsilon$ is sufficiently small), $C\|\nabla u\|_{3,2, Q_{r}}, C\left(\left\|\nabla u_{1}\right\|_{p, q, Q_{r}}+\left\|\nabla u_{2}\right\|_{p, q, Q_{r}}\right)$ and $C\left(\left\|\nabla u_{1}\right\|_{p, 2, Q_{r}}+\left\|\nabla u_{2}\right\|_{p, 2, Q_{r}}\right)$ can be made smaller than 1 by diminishing $r$. In any case we have $V \equiv 0$ and $v=\tilde{v}$. Therefore, $v$ solves the equations (3.1) (3.4) and $v, h^{i}$ and $B_{i}(u, v)$ are from $L^{l, l^{\prime}}$, where $l, l^{\prime}$ fulfil the conditions from 3.5) and $l \in(1, p)$ if $i=3$. It follows from Lemma 2.2 that

$$
\nabla v \in L^{\alpha, \alpha^{\prime}}
$$

for every $\alpha \in[l, \infty), \alpha^{\prime} \in\left[l^{\prime}, \infty\right)$ such that $2 / \alpha^{\prime}+3 / \alpha=2$. Thus, by the choice $\alpha=l$ and $\alpha^{\prime}=2 l /(2 l-3)$, we have that

$$
\nabla v \in L^{l, \frac{2 l}{2 l-3}}
$$

Since $v=0$ on $\partial \Omega \times(0, T)$, we have immediately that $v \in L^{\frac{3 l}{3-l}, \frac{2 l}{2 l-3}}$ and that

$$
3 \frac{3-l}{3 l}+2 \frac{2 l-3}{2 l}=1
$$

By the definition of $v, v=u$ in a space-time neighborhood of $\left(x_{0}, t_{0}\right)$. We can now use Theorem 1.1 and the proof of Theorem 1.2 is complete.

Remark 3.2. The condition (A3) in Theorem 1.2 can be replaced by the condition
(A3') $\nabla u_{1}, \frac{\partial u_{2}}{\partial x_{2}}, \frac{\partial u_{2}}{\partial x_{3}}, \frac{\partial u_{3}}{\partial x_{2}} \in L^{p, q}\left(Q_{r}\right), p \in(3 / 2, \infty], q \in(2, \infty], 3 / p+2 / q \leq 2$
or by the more general condition
$\frac{\partial u_{i}}{\partial x_{j}} \in L^{p_{j}^{i}, q_{j}^{i}}\left(Q_{r}\right), p_{j}^{i} \in(3 / 2, \infty], q_{j}^{i} \in(2, \infty], 3 / p_{j}^{i}+2 / q_{j}^{i} \leq 2$, for $i=1,2$ and $j=1,2,3$.

Similarly, the condition (A4) from Theorem 1.2 can be replaced by the condition
(A4') $\nabla u_{1}, \frac{\partial u_{2}}{\partial x_{2}}, \frac{\partial u_{2}}{\partial x_{3}}, \frac{\partial u_{3}}{\partial x_{2}} \in L^{p, q}\left(Q_{r}\right), p \in(3, \infty], q=2$.

## References

[1] D.Chae, H.J. Choe, Regularity of Solutions to the Navier-Stokes equations, Electronic Journal of Differential Equations 1999 No. 05 (1999), 1-7.
[2] H.J. Choe, Boundary regularity of weak solutions of the Navier-Stokes equations, J. of Differential Equations 149 (1998), 211-247.
[3] G.P. Galdi, An introduction to the mathematical theory of the Navier-Stokes equations. Vol. I. Linearized steady problems, Springer Tracts in Natural Philosophy, 38. Springer-Verlag, New York, (1994).
[4] G.P. Galdi, An Introduction to the Navier-Stokes initial-boundary value problem, in Fundamental Directions in Mathematical Fluid Mechanics, editors G.P. Galdi, J. Heywood and R. Rannacher, series "Advances in Mathematical Fluid Mechanics", Birkhauser-Verlag, Basel (2000), 1-98.
[5] Y. Giga, H. Sohr, Abstract $L^{p}$ estimates for the Cauchy problem with applications to the Navier-Stokes equations in exterior domains, J. of Functional Analysis 102 (1991), 72-94.
[6] K. Kang, Preprint, (2004) 1-33.
[7] H. Kozono, Uniqueness and Regularity of Weak Solutions to the Navier-Stokes Equations, Lecture Notes in Num. Appl. Anal. 16 (1998), 161-208.
[8] A. Kufner, O. John, S.Fučík, Function spaces, Academia, Prague, (1977).
[9] J. Neustupa, The boundary regularity of a weak solution of the Navier-Stokes equation and its connection with the interior regularity of pressure, Applications of Mathematics 48 (2003) , 547-558.
[10] G.A. Seregin, Local regularity of suitable weak solutions to the Navier-Stokes equations near the boundary, J. Math. Fluid Mech 4 (2002), 1-29.
[11] Z.Skalák, Regularity of Weak Solutions of the Navier-Stokes equations near the Smooth Boundary, accepted to Electronic Journal of Differential Equations.
[12] S. Takahashi, On a regularity criterion up to the boundary for weak solutions of the NavierStokes equations, Comm. in Partial Differential Equations 17 (1992), 261-285.
[13] S. Takahashi, Erratum to "On a regularity criterion up to the boundary for weak solutions of the Navier-Stokes equations", Comm. in Partial Differential Equations 19 (1994), 1015-1017.
[14] R. Temam, Navier-Stokes equations, theory and numerical analysis, North@-Holland Publishing Company, Amsterodam, New York, Oxford, (1979).

Petr Kučera
Department of Mathematics, Faculty of Civil Engineering, Czech Technical University, Thákurova 7, 16629 Prague 6, Czech Republic

E-mail address: kucera@mat.fsv.cvut.cz
Zdeněk Skalák
Institute of Hydrodynamics, Czech Academy of Sciences, Pod Paťankou 30/5, 16612
Prague 6, Czech Republic
E-mail address: skalak@ih.cas.cz, skalak@mat.fsv.cvut.cz


[^0]:    2000 Mathematics Subject Classification. 35Q35, 35B65.
    Key words and phrases. Navier-Stokes equations; weak solutions; boundary regularity. (C) 2006 Texas State University - San Marcos. Submitted May 20, 2005. Published July 10, 2006.
    The research was supported by the research plan of the Ministry of Education of the Czech Republic No. 6840770010 (the first author), the Grant Agency of AS CR through the grant IAA100190612 (the first author) and by the Grant Agency of AS CR through the grant IAA100190612 (Inst. Res. Plan AV0Z20600510) (the second author).

